

MIT Origin, Destination, and Transfer Inference (ODX)

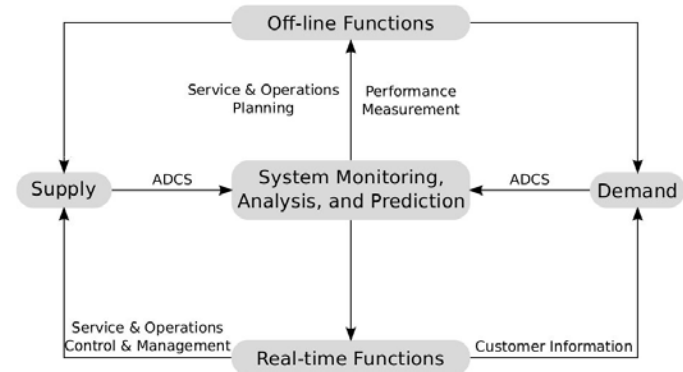
- Using automatically collected data: AFC, AVL, APC
- Infers destinations in open systems
- Infers transfers
- Only captures existing demand
- Does not make inferences for all fare transactions
 - only one tap
 - cash
 - fare evasion
 - trips on other modes
- Validated with surveys
- Needs to be scaled up to full demand

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MIT Key Automated Data Collection Systems

- Automatic Vehicle Location (AVL)
- Automatic Fare Collection (AFC)
- Automatic Passenger Counting (APC)

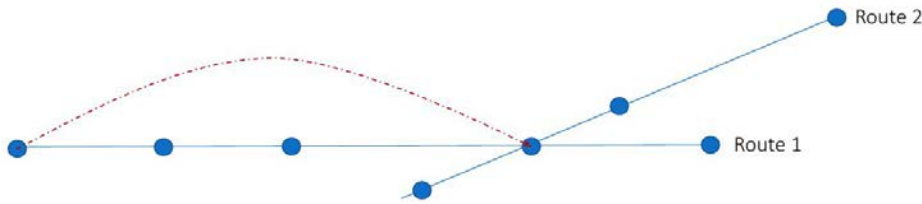


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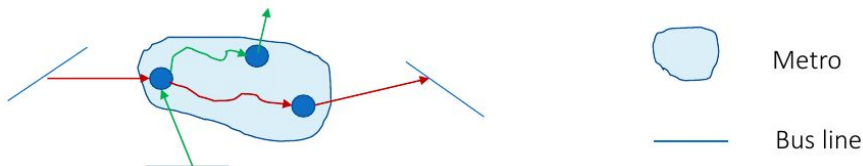
MIT OD Matrix Estimation

Route Level



Network Level

Full Intermodal Journey Inference



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MIT Route Level OD Estimation with APC

APC provides “control totals”

TIME	BUS ID	ROUTE	TRIP ID	DIRECTION	Boardings	Alightings	STOP
9/12/2005 12:08:10 AM	6734	20	15065450	East	0	3	WASHINGTON + STATE
9/12/2005 12:00:04 AM	6734	20	15065450	East	1	1	MADISON + PEORIA
9/12/2005 12:03:29 AM	6734	20	15065450	East	0	0	WASHINGTON + CANAL
9/12/2005 5:37:19 AM	6729	20	15067244	East	0	1	WASHINGTON + LASALLE

Route #1 APC + seed matrix		Destination				
		Stop 1	Stop 2	Stop 3	Stop 4	Target on
Origin	Stop 1		25	10	2	40
	Stop 2			5	15	30
	Stop 3				9	20
	Stop 4					
Target off		0	30	20	40	90

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Iterative Proportional Fitting (IPF)

- Also known as biproportional fitting and matrix scaling
- Scales cell values of a sampled origin-destination matrix so that row and column sums equal marginal target values (counted boardings and alightings)
- If all values are strictly positive, IPF converges to a unique MLE solution
- Zeroes affect the solution

Initialization						
	A	B	C	D	Total Boardings	Target Boardings
A		1	1	1	3	40
B			1	1	2	30
C				1	1	20
D						
Total Alightings		1	2	3		
Target Alightings		30	20	40		90

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Iterative Proportional Fitting (IPF)

Step 1							
	A	B	C	D	Total Boardings	Target Boardings	Factor
A		13.3	13.3	13.3	40	40	13.3
B			15	15	30	30	15.0
C				20	20	20	20.0
D							
Total Alightings		13.3	28.3	48.3			
Target Alightings		30	20	40			

Step 2							
	A	B	C	D	Total Boardings	Target Boardings	
A		30	9.41	11	50.4	40	
B			10.6	12.4	23.0	30	
C				16.6	16.6	20	
D							
Total Alightings		30	20	40			
Target Alightings		30	20	40			
Factor		2.3	0.7	0.8			

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Iterative Proportional Fitting (IPF)

Step 3							
	A	B	C	D	Total Boardings	Target Boardings	Factor
A		23.8	7.46	8.75	40	40	0.8
B			13.8	16.2	30	30	1.3
C				20	20	20	1.2
D							
Total Alightings		23.8	21.3	44.9			
Target Alightings		30	20	40			

Step 4							
	A	B	C	D	Total Boardings	Target Boardings	
A		30	7.02	7.79	44.8	40	
B			13	14.4	27.4	30	
C				17.8	17.8	20	
D							
Total Alightings		30	20	40			
Target Alightings		30	20	40			
Factor		1.3	0.9	0.9			

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Iterative Proportional Fitting (IPF)

Step 5							
	A	B	C	D	Total Boardings	Target Boardings	Factor
A		26.8	6.26	6.95	40	40	0.9
B			14.2	15.8	30	30	1.1
C				20	20	20	1.1
D							
Total Alightings		26.8	20.5	42.7			
Target Alightings		30	20	40			

Step 6							
	A	B	C	D	Total Boardings	Target Boardings	
A		30	6.12	6.51	42.6	40	
B			13.9	14.8	28.7	30	
C				18.7	18.7	20	
D							
Total Alightings		30	20	40			
Target Alightings		30	20	40			
Factor		1.1	1.0	0.9			

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Iterative Proportional Fitting (IPF)

Step 7							
	A	B	C	D	Total Boardings	Target Boardings	Factor
A		28.2	5.74	6.11	40	40	0.9
B			14.5	15.5	30	30	1.0
C				20	20	20	1.1
D							
Total Alightings		28.2	20.3	41.6			
Target Alightings		30	20	40			
Step 8							
	A	B	C	D	Total Boardings	Target Boardings	
A		30	5.66	5.88	41.5	40	
B			14.3	14.9	29.2	30	
C				19.2	19.2	20	
D							
Total Alightings		30	20	40			
Target Alightings		30	20	40			
Factor		1.1	1.0	1.0			

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Iterative Proportional Fitting (IPF)

Step 9							
	A	B	C	D	Total Boardings	Target Boardings	Factor
A		28.9	5.45	5.66	40	40	1.0
B			14.7	15.3	30	30	1.0
C				20	20	20	1.0
D							
Total Alightings		28.9	20.2	40.9			
Target Alightings		30	20	40			
Step 10							
	A	B	C	D	Total Boardings	Target Boardings	
A		30	5.41	5.53	40.9	40	
B			14.6	14.9	29.5	30	
C				19.5	19.5	20	
D							
Total Alightings		30	20	40			
Target Alightings		30	20	40			
Factor		1.0	1.0	1.0			

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Iterative Proportional Fitting (IPF)

Step 11							
	A	B	C	D	Total Boardings	Target Boardings	Factor
A		29.3	5.28	5.4	40	40	1.0
B			14.8	15.2	30	30	1.0
C				20	20	20	1.0
D							
Total Alightings		29.3	20.1	40.6			
Target Alightings		30	20	40			
Step 12							
	A	B	C	D	Total Boardings	Target Boardings	
A		30	5.25	5.33	40.6	40	
B			14.7	15	29.7	30	
C				19.7	19.7	20	
D							
Total Alightings		30	20	40			
Target Alightings		30	20	40			
Factor		1.0	1.0	1.0			

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Route Level ODX with AFC and AVL

	TfL	MBTA	Seoul
AFC Rail	Closed	Open	Closed, Detailed, Including transfers
AFC Bus	Open	Open	
AVL	iBus	Announcements Heartbeat Time points	
Control totals	ETM (Buses)	APC (sample)	
	Gatelines (Rail stations)	some	

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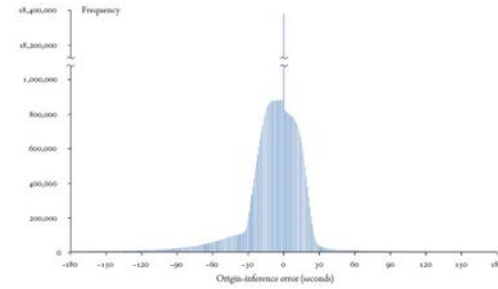
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MIT Origin Inference

Matching the AFC transactions with the AVL data to infer boarding stops



MIT Origin Inference Results: London

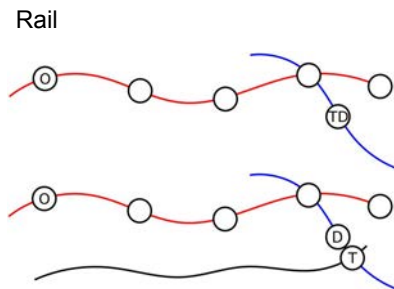
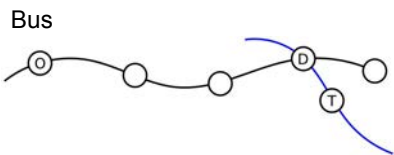


- 10 weekdays, 6.1 to 6.5 million Oyster bus boardings per day
- 96% of boarding locations inferred within ± 5 min
 - 96% within ± 2 min
 - 93% within ± 1 min
 - 28% between arrival and departure times
- 2.6% beyond ± 5 min.
- 1.4% not matched to iBus route or trip

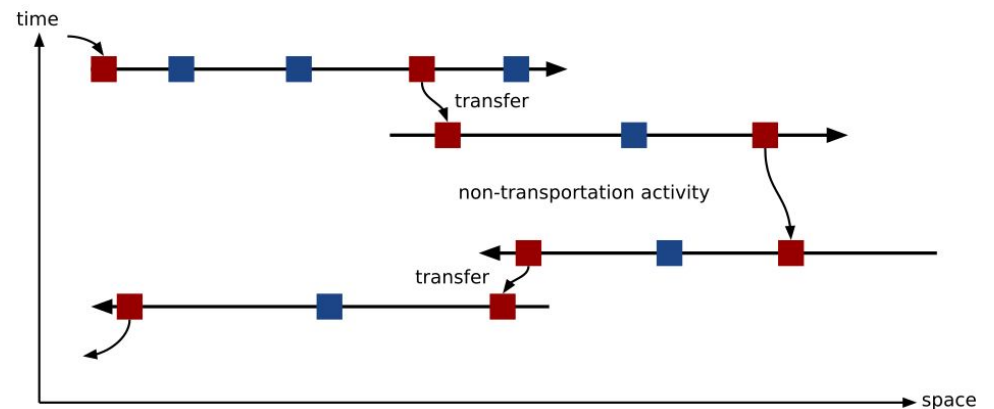
MIT Destination Inference: Closest Stop

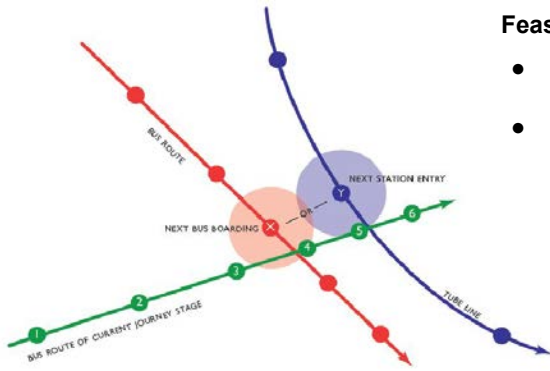
Key Assumptions

- The destination of many trip segments is close to the origin of the following trip segment.
- No intermediate private transportation mode trip segment
- Passengers will not walk a long distance
- Last trip of a day ends at the origin of the first trip of the day (symmetry assumption)



MIT Destination Inference



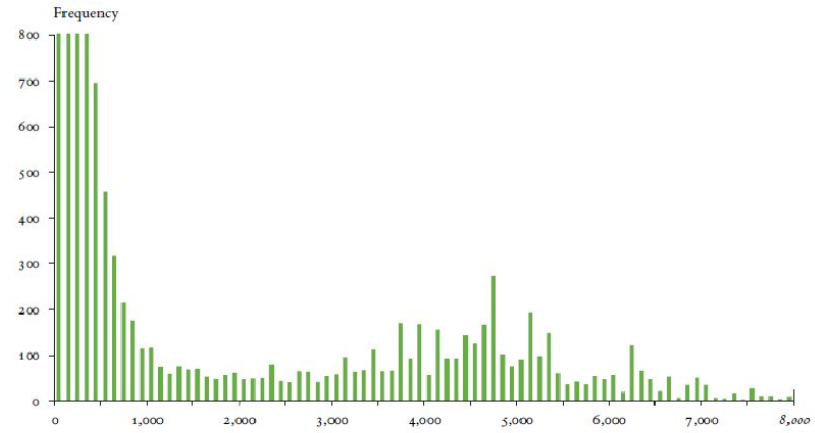


Feasibility Tests

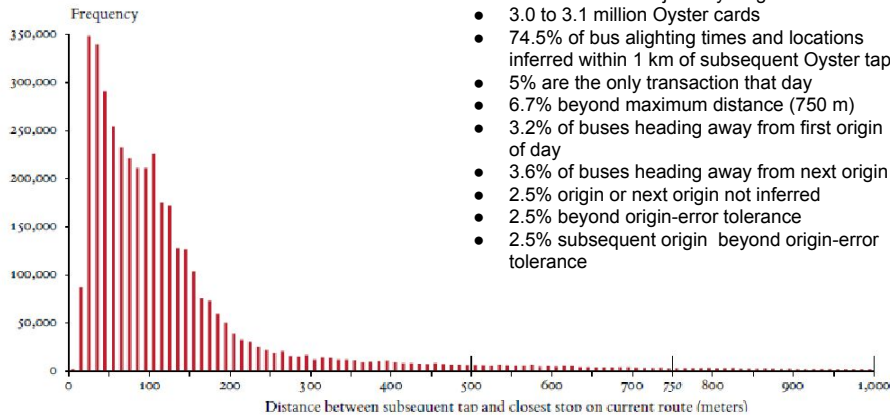
- distance and time between alighting and next boarding stop
- relative location

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Destination inference: 74.6%



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Ten-weekday average: 6-10 and 13-17 June 2011

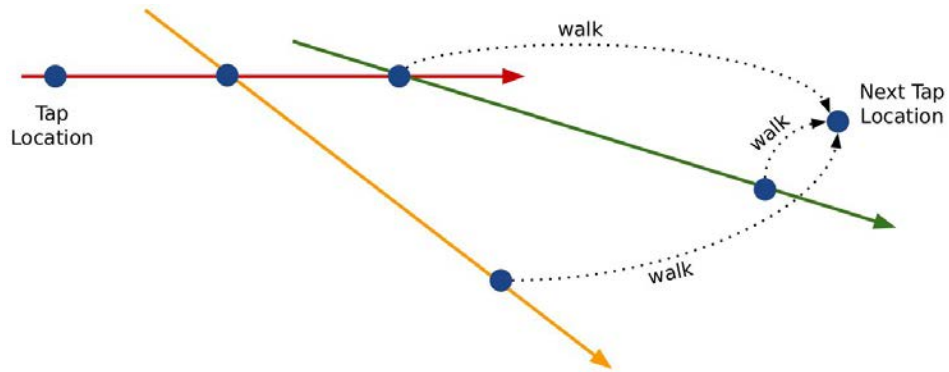
- 15.6 to 16.1 million Oyster transactions
- 9.5 to 10.1 million journey stages
- 3.0 to 3.1 million Oyster cards
- 74.5% of bus alighting times and locations inferred within 1 km of subsequent Oyster tap
- 5% are the only transaction that day
- 6.7% beyond maximum distance (750 m)
- 3.2% of buses heading away from first origin of day
- 3.6% of buses heading away from next origin
- 2.5% origin or next origin not inferred
- 2.5% beyond origin-error tolerance
- 2.5% subsequent origin beyond origin-error tolerance

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- Small stop-by-stop differences between estimated OD and results from the Bus OD Survey (BODS)
- BODS underestimated the ridership in peak periods and midday, especially when BODS survey return rates are low (50%-80%).
- Value for transportation planning

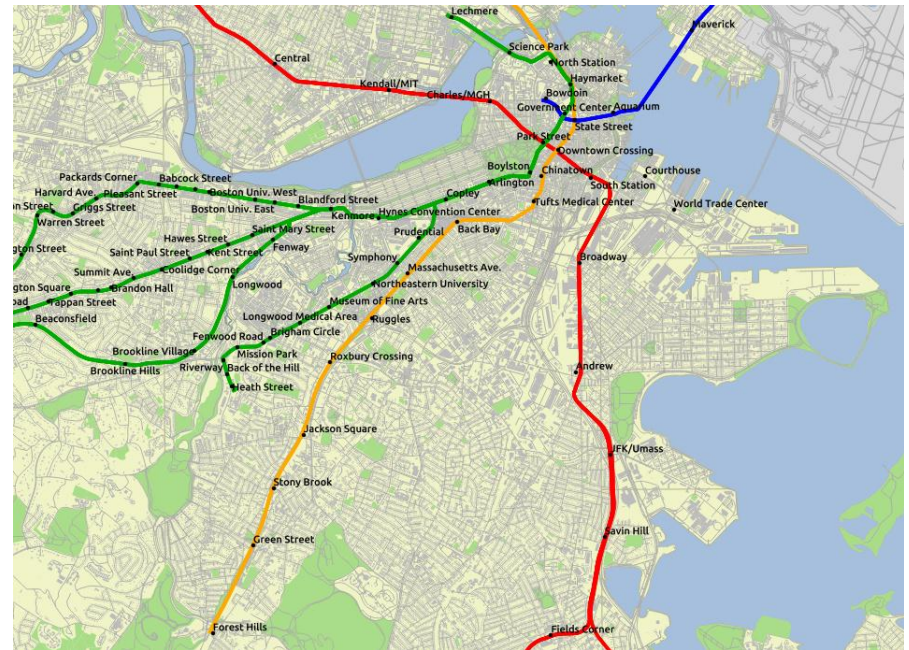
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MIT Destination Inference: Minimum Cost Path



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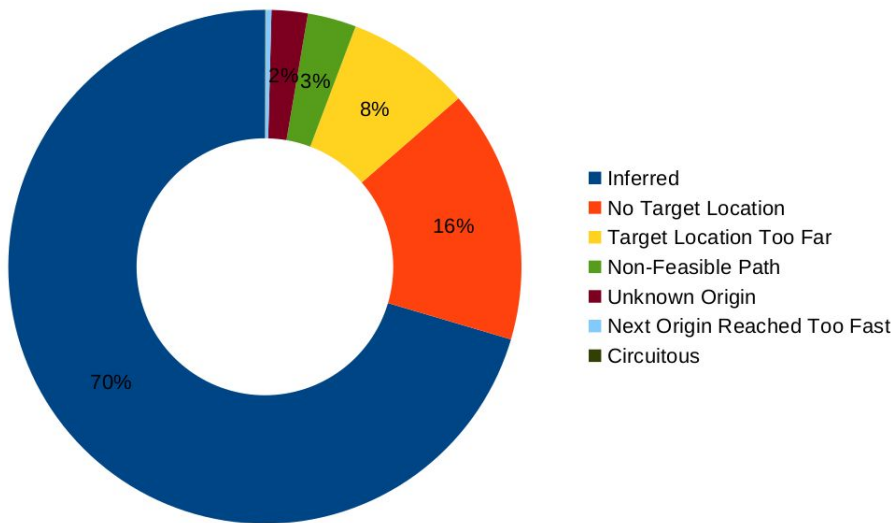
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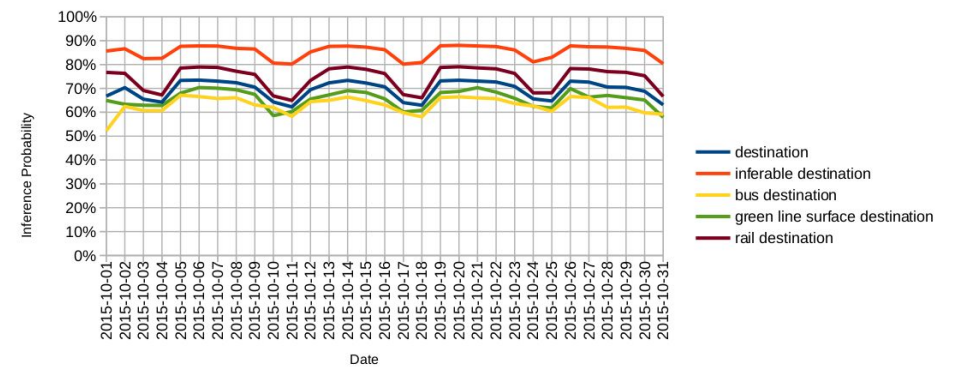
MIT Destination Inference: MBTA



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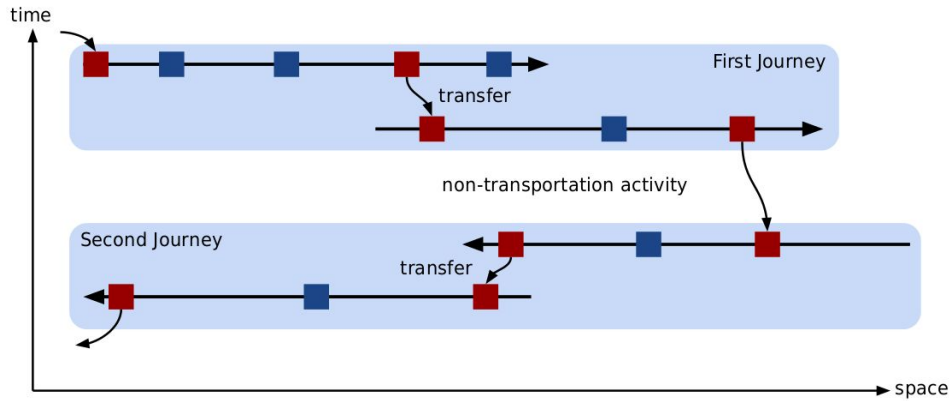
MIT Inference Probability



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MIT Interchange (Transfer) Inference



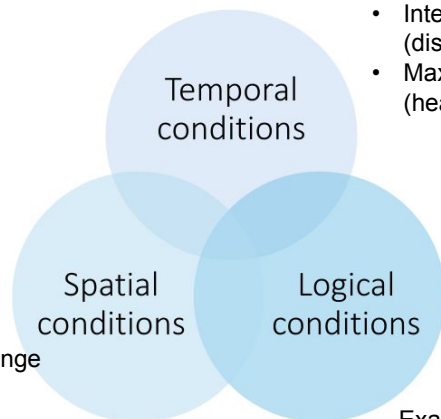
MIT Interchange (Transfer) Inference

Journey stage: any portion of a rider's journey that is represented by a single Oyster bus record or by a rail entry/exit pair.

Interchange (Transfer): a transition between two consecutive journey stages that does not contain a trip-generating activity. Its primary purpose, rather, is to connect a previous stage's origin to a subsequent stage's destination.

Full journey: a sequential set of journey stages connected exclusively through interchanges.

MIT Trip-Linking Assumptions



- Examples:
- Interchange time (distance)
 - Maximum bus wait time (headways)

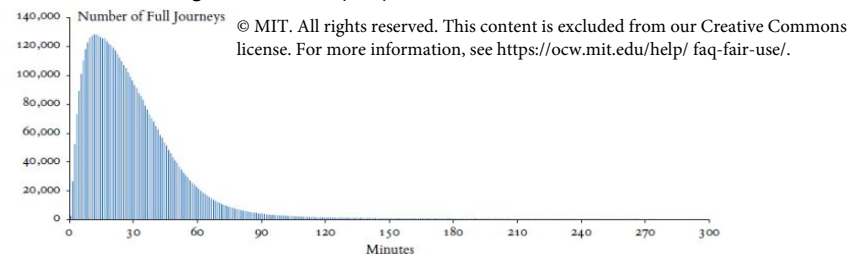
- Examples:
- Maximum interchange distance
 - Circuity between stages
 - Ending journey near origin

- Example:
- Must not continue at same station, same route, etc.

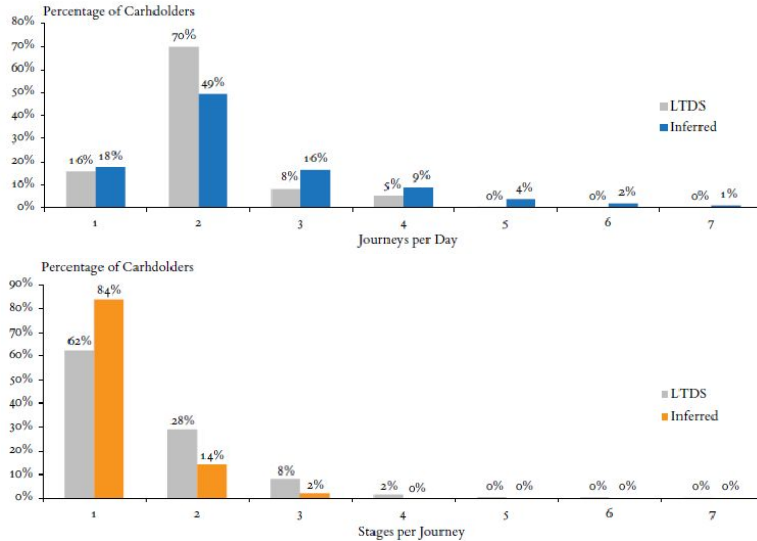
MIT Interchange Inference Results

Ten-day average: 6-10 and 13-17 June 2011

- Link status inferred for 91% of journey stages
 - link status could not be inferred for remaining 9% of stages: assumed not linked
- Stages per journey:
 - one stage: 4 million (66%)
 - two stages: 1.5 million (25%)
 - three stages: 400,000 (7%)
 - four or more stages: 170,000 (3%)



MIT Comparison to Travel Surveys (LTDS)



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MIT Trip-Level Scaling

- AFC, AVL, and ODX give an OD matrix, but only for a sample of passenger trips
- APC gives full count of boardings and alightings
 - for all vehicles, a fraction of vehicles, or none
- Iterative Proportional Fitting (IPF) can be used to assign remaining destinations in probability
 - control totals are APC boardings and alightings minus ODX boardings and alightings

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MIT Trip-Level Scaling with Transfer Information and without APC

- The complete OD matrix \mathbf{R} can be divided into an inferred part \mathbf{I} and a missing part \mathbf{M} .

$$\mathbf{R} = \mathbf{I} + \mathbf{M}$$

- The missing part can be divided into trips with uninferred destinations \mathbf{U} and trips not observed \mathbf{N} .

$$\mathbf{M} = \mathbf{U} + \mathbf{N}$$

- Therefore

$$\mathbf{R} = \mathbf{I} + \mathbf{U} + \mathbf{N}$$

and we want to estimate \mathbf{R} as

$$\tilde{\mathbf{R}} = \mathbf{I} + \tilde{\mathbf{U}} + \tilde{\mathbf{N}}$$

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MIT Trip-Level Scaling with Transfer Information and without APC

- Trips followed by transfers may have different OD structure.
- Assume that all observed trips followed by a transfer have an inferred destination, i.e. no trips followed by a transfer in \mathbf{U} .
- Destinations of uninferred trips in \mathbf{U} should be scaled excluding trips followed by a transfer.
- Let \mathbf{u} be a vector of boardings with uninferred destinations.
- Let $\bar{\mathbf{L}}$ be a matrix of destination probability distributions for each origin for trips not followed by a transfer.
- The uninferred part \mathbf{U} is estimated by

$$\tilde{\mathbf{U}} = \mathbf{u}\bar{\mathbf{L}}$$

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Mit Trip-Level Scaling with Transfer Information and without APC

- A portion of trips \tilde{N} is not observed.
 - Trips with uninferred origins
 - Trips without farebox interaction
- They can be estimated by combining ODX with passenger counts, e.g. APC data.
- Let \bar{n} be a vector of boarding scaling factors.
- Assuming destinations are distributed like observed trips,

$$\tilde{N} = \bar{n} (\mathbf{I} + \tilde{U})$$

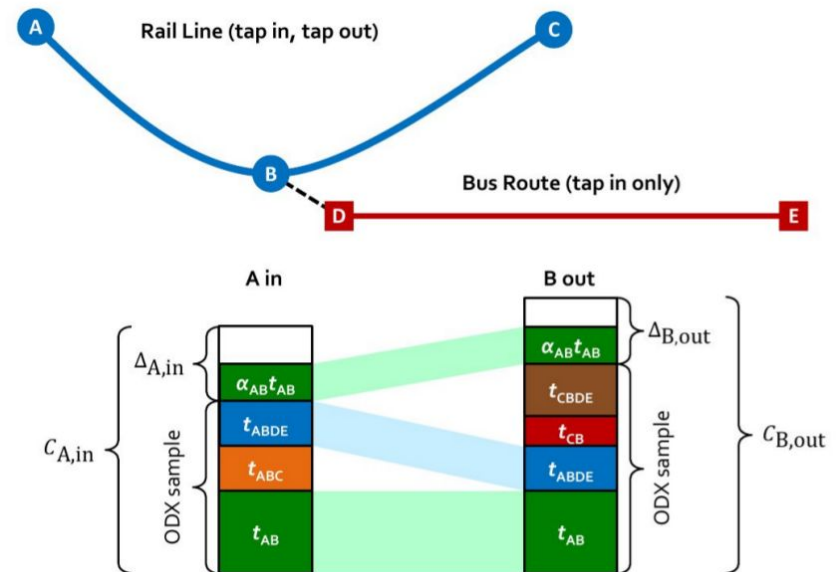
Mit Trip-Level Scaling with Transfer Information and without APC

$$\begin{aligned} \tilde{R} &= \mathbf{I} + \tilde{U} + \tilde{N} \\ &= \mathbf{I} + \tilde{U} + \bar{n} (\mathbf{I} + \tilde{U}) \\ &= (\mathbf{1} + \bar{n}) (\mathbf{I} + \tilde{U}) \\ &= (\mathbf{1} + \bar{n}) (\mathbf{I} + \mathbf{u}\bar{L}) \end{aligned}$$

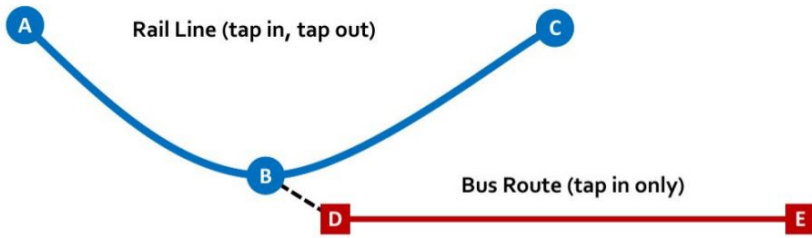
Mit Journey Matrix Scaling

- Problem
 - Estimate expansion factors to scale Oyster-inferred full-journeys to represent non-Oyster and incompletely documented Oyster journeys.
- Challenges
 - Control totals available for stations, routes, but not itineraries
 - Large number of unique itineraries observed per day (if bus activity is aggregated to the route level)
 - Trillions of solutions can satisfy control totals
- Approach
 - Scale all full-journey itineraries to satisfy control totals

Mit Journey Matrix Scaling



MIT Journey Matrix Scaling



Count Node		Itinerary					
Station/Stop	Movement	AB	ABC	ABDE	CB	CBDE	DE
A	in	1	1	1	0	0	0
B	out	1	0	1	1	1	0
C	in	0	0	0	1	1	0
C	out	0	1	0	0	0	0
D	in	0	0	1	0	1	1

binary location-itinerary incidence matrix **B**

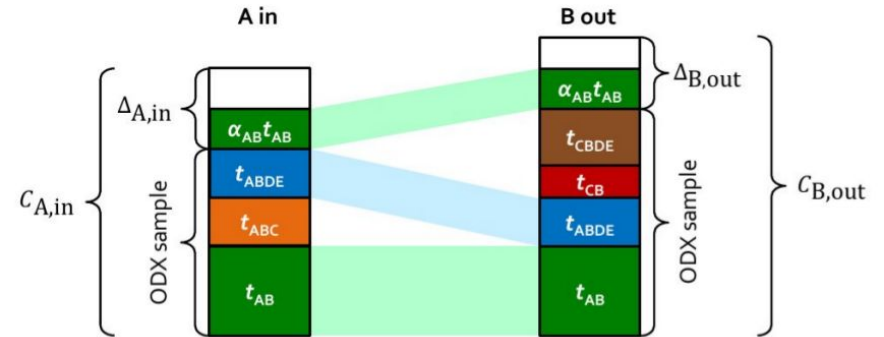
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MIT Journey Matrix Scaling

$$T_i = (1 + \alpha_i)t_i \quad \forall i \in I$$

$$\Delta_n = C_n - \sum_{i \in I} t_i b_{n,i} = \sum_{i \in I} t_i \alpha_i b_{n,i} \quad \forall n \in N$$



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MIT Journey Matrix Scaling

Initialize:

$$\hat{\alpha}_i \leftarrow 1.0 \quad \forall i \in I$$

Update:

$$\hat{\Delta}_n \leftarrow \sum_{i \in I} b_{n,i} \hat{\alpha}_i t_i \quad \forall n \in N$$

$$\hat{\alpha}_i \leftarrow \hat{\alpha}_i \frac{\sum_{n \in N} b_{n,i} \frac{\Delta_n}{\hat{\Delta}_n}}{\sum_{n \in N} b_{n,i}} \quad \forall i \in I$$

Count Location		Itinerary						Totals		
Station/Stop	Movement	AB	ABC	ABDE	CB	CBDE	DE	$\Delta_{\hat{}}$	Δ	Control
A	in	1	1	1	0	0	0	-	102	400
B	out	1	0	1	1	1	0	-	116	450
C	in	0	0	0	1	1	0	-	38	150
C	out	0	1	0	0	0	0	-	24	100
D	in	0	0	1	0	1	1	-	90	350
α		1.00	1.00	1.00	1.00	1.00	1.00			
αt		74	76	148	38	74	38			
$(1+\alpha)t$		148	152	296	76	148	76			

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MIT Journey Matrix Scaling

Initialize:

$$\hat{\alpha}_i \leftarrow 1.0 \quad \forall i \in I$$

Update:

$$\hat{\Delta}_n \leftarrow \sum_{i \in I} b_{n,i} \hat{\alpha}_i t_i \quad \forall n \in N$$

$$\hat{\alpha}_i \leftarrow \hat{\alpha}_i \frac{\sum_{n \in N} b_{n,i} \frac{\Delta_n}{\hat{\Delta}_n}}{\sum_{n \in N} b_{n,i}} \quad \forall i \in I$$

Count Location		Itinerary						Totals		
Station/Stop	Movement	AB	ABC	ABDE	CB	CBDE	DE	$\Delta_{\hat{}}$	Δ	Control
A	in	1	1	1	0	0	0	298	102	400
B	out	1	0	1	1	1	0	334	116	450
C	in	0	0	0	1	1	0	112	38	150
C	out	0	1	0	0	0	0	76	24	100
D	in	0	0	1	0	1	1	260	90	350
α		1.00	1.00	1.00	1.00	1.00	1.00			
αt		74	76	148	38	74	38			
$(1+\alpha)t$		148	152	296	76	148	76			

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MIT Journey Matrix Scaling

Initialize:

$$\hat{\alpha}_i \leftarrow 1.0 \quad \forall i \in I$$

Update:

$$\hat{\Delta}_n \leftarrow \sum_{i \in I} b_{n,i} \hat{\alpha}_i t_i \quad \forall n \in N$$

$$\hat{\alpha}_i \leftarrow \hat{\alpha}_i \frac{\sum_{n \in N} b_{n,i} \frac{\Delta_n}{\hat{\Delta}_n}}{\sum_{n \in N} b_{n,i}} \quad \forall i \in I$$

Count Location		Itinerary						Totals		
Station/Stop	Movement	AB	ABC	ABDE	CB	CBDE	DE	$\Delta_{\hat{}}$	Δ	Control
A	in	1	1	1	0	0	0	298	102	400
B	out	1	0	1	1	1	0	334	116	450
C	in	0	0	0	1	1	0	112	38	150
C	out	0	1	0	0	0	0	76	24	100
D	in	0	0	1	0	1	1	260	90	350
α		0.34	0.33	0.35	0.34	0.34	0.35			
αt		26	25	51	13	25	13			
$(1+\alpha)t$		100	101	199	51	99	51			

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MIT Journey Matrix Scaling

Initialize:

$$\hat{\alpha}_i \leftarrow 1.0 \quad \forall i \in I$$

Update:

$$\hat{\Delta}_n \leftarrow \sum_{i \in I} b_{n,i} \hat{\alpha}_i t_i \quad \forall n \in N$$

$$\hat{\alpha}_i \leftarrow \hat{\alpha}_i \frac{\sum_{n \in N} b_{n,i} \frac{\Delta_n}{\hat{\Delta}_n}}{\sum_{n \in N} b_{n,i}} \quad \forall i \in I$$

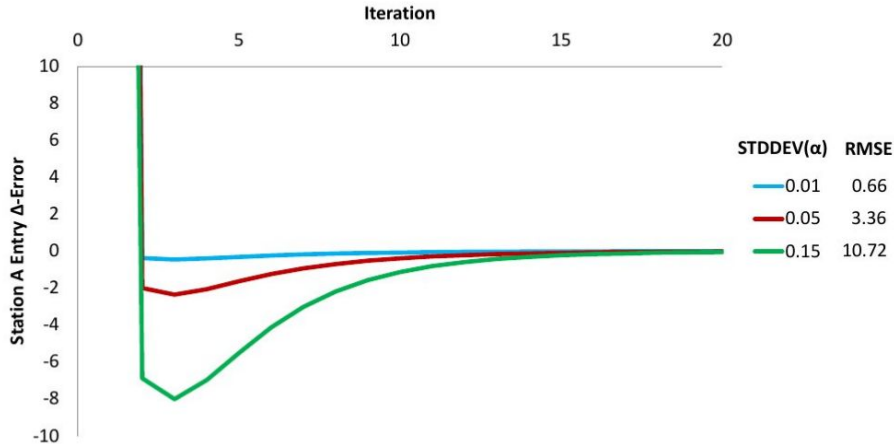
Count Location		Itinerary						Totals		
Station/Stop	Movement	AB	ABC	ABDE	CB	CBDE	DE	$\Delta_{\hat{}}$	Δ	Control
A	in	1	1	1	0	0	0	102	102	400
B	out	1	0	1	1	1	0	115	116	450
C	in	0	0	0	1	1	0	38	38	150
C	out	0	1	0	0	0	0	25	24	100
D	in	0	0	1	0	1	1	90	90	350
α		0.35	0.32	0.35	0.34	0.34	0.35			
αt		26	24	52	13	25	13			
$(1+\alpha)t$		100	100	200	51	99	51			

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MIT Journey Matrix Scaling

Convergence of Journey Matrix Scaling Heuristic vs. Standard Deviation of α Across Itineraries

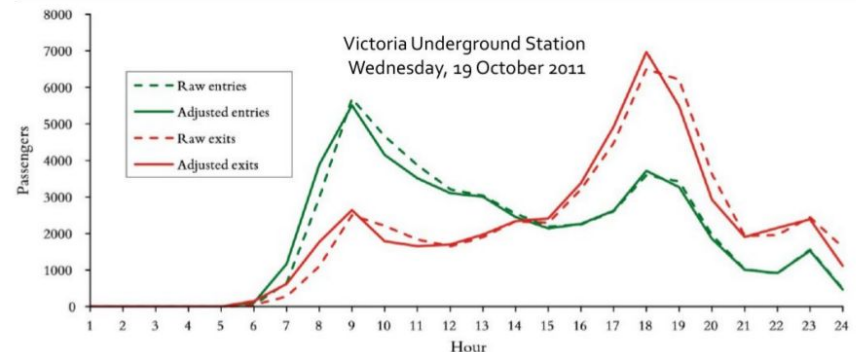


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MIT Journey Matrix Scaling

Recording Period	Period Offset				Unadjusted Count	Period Offset				Adjusted Count
	0	1	2	3		0	1	2	3	
5	100.0%	0.0%	0.0%	0.0%	1	1	0	0	0	22
6	66.7%	33.3%	0.0%	0.0%	59	39	20	0	0	199
7	64.7%	35.0%	0.3%	0.0%	444	287	155	1	0	...
8	59.4%	40.1%	0.5%	0.0%	803	477	322	4	0	...
9	47.7%	50.6%	1.7%	0.0%	803	383	406	14	0	...

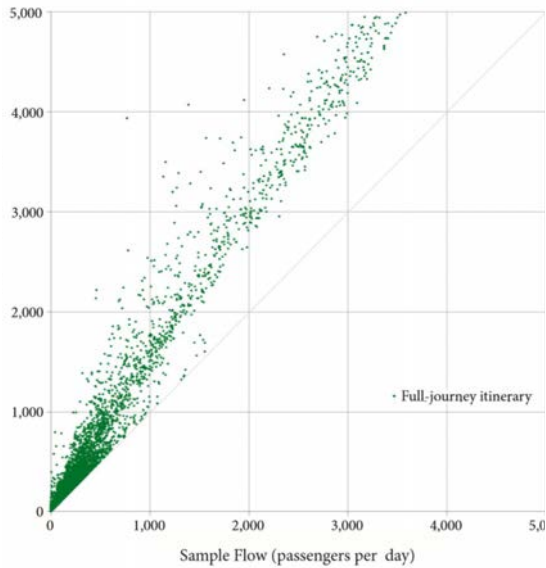


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MIT Scaling Factor Results

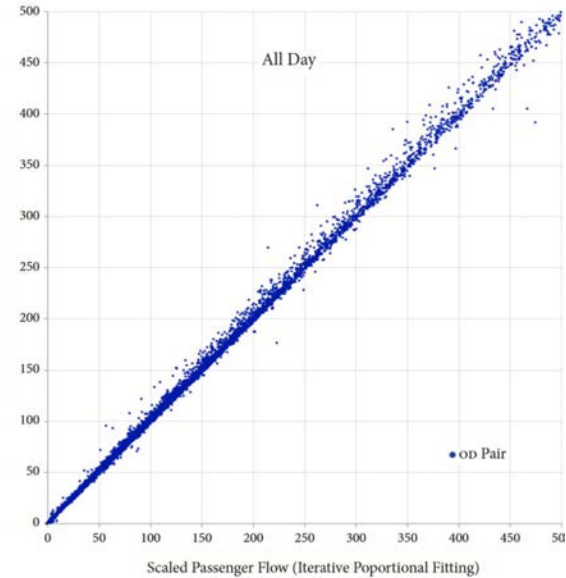


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MIT Journey Scaling vs. IPF (rail links only)

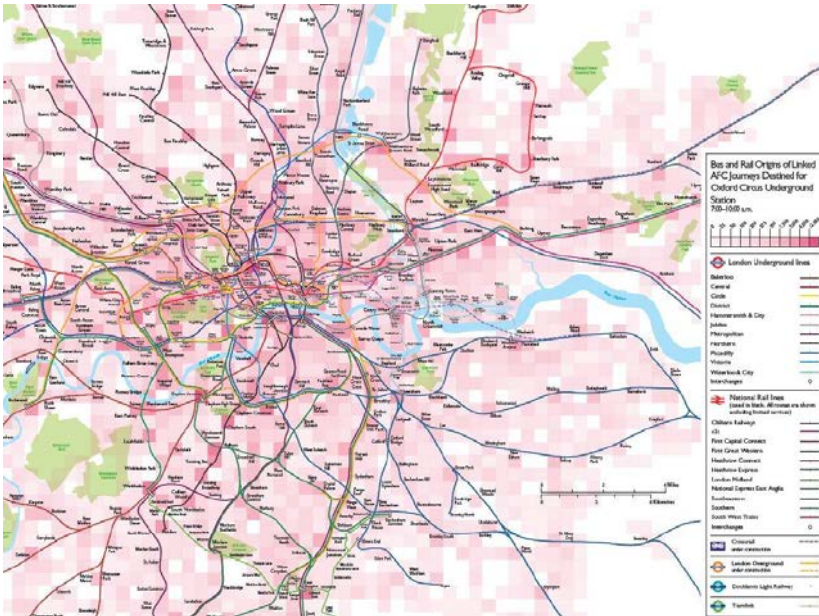


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MIT Full-Journey Scaling Results



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