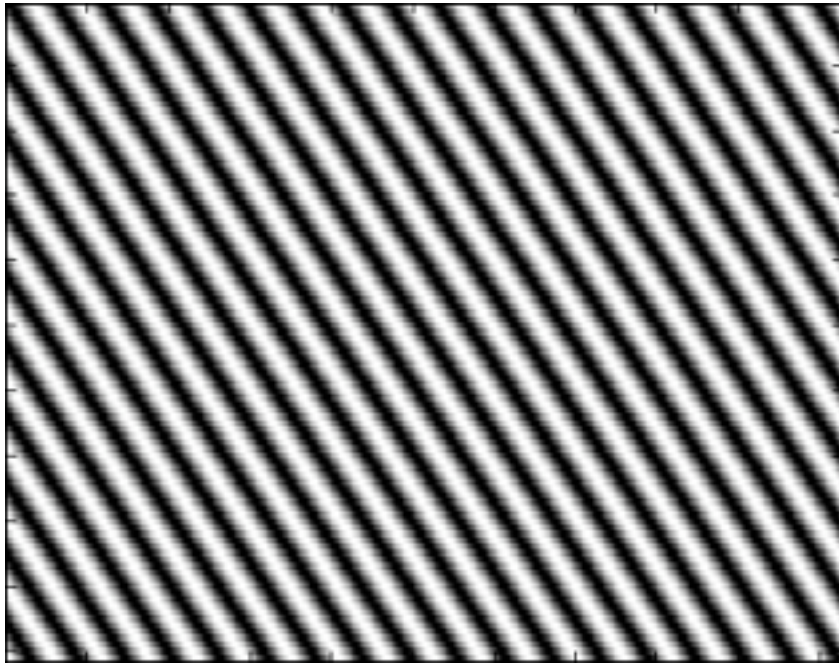


The 3D wave equation

In three-dimensions, the Wave Equation is generalized as

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} - \frac{1}{c^2} \frac{\partial^2 f}{\partial t^2} = 0.$$

Our familiar plane and spherical waves are special solutions.

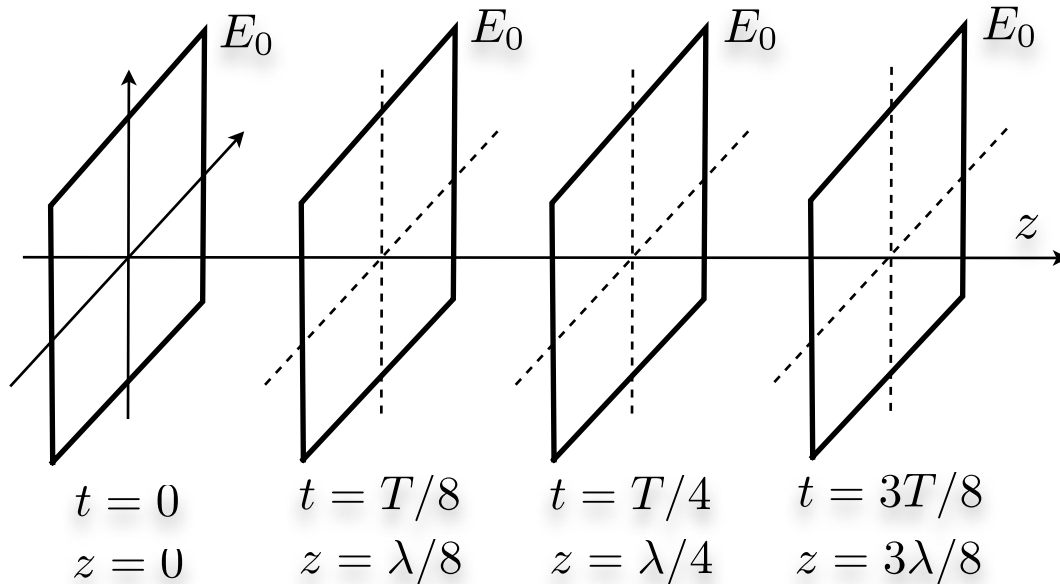


Plane wave



Spherical wave

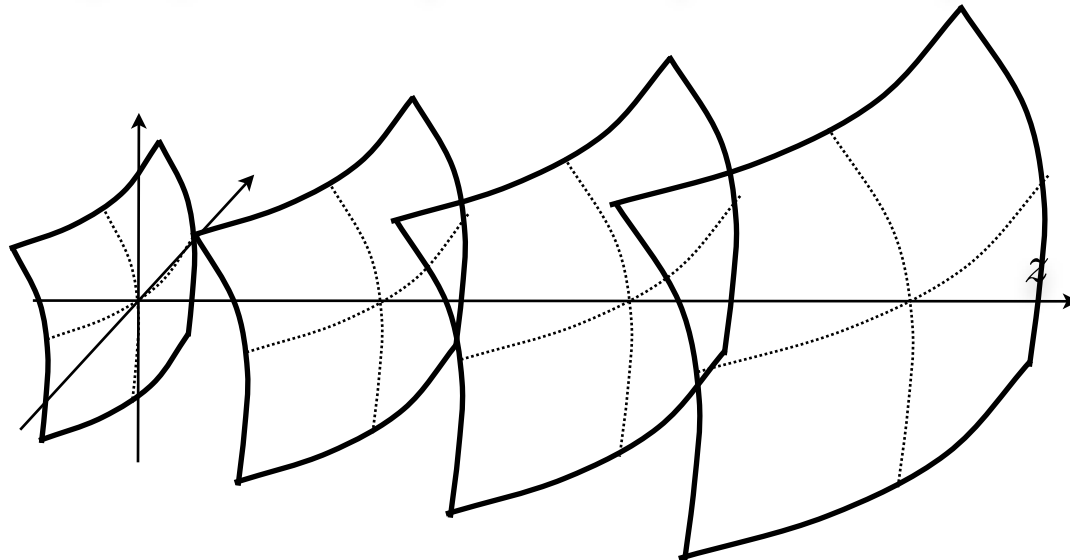
Planar and Spherical Wavefronts



Planar wavefront (plane wave):

The wave phase is constant along a **planar** surface (the wavefront).

As time evolves, the wavefronts propagate at the wave speed without changing; we say that the wavefronts are *invariant to propagation* in this case.

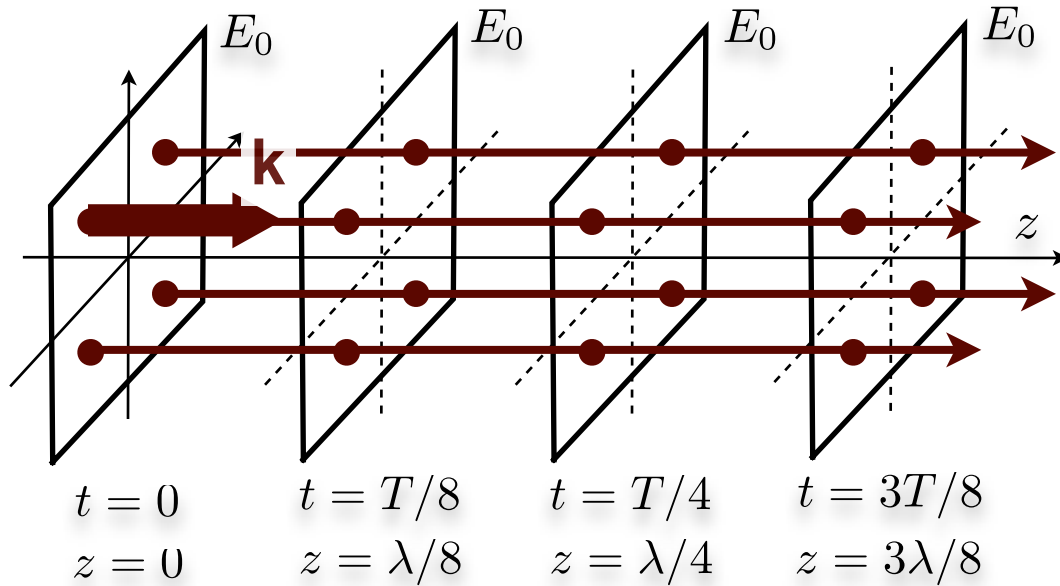


Spherical wavefront (spherical wave):

The wave phase is constant along a **spherical** surface (the wavefront).

As time evolves, the wavefronts propagate at the wave speed and expand outwards while preserving the wave's energy.

Wavefronts, rays, and wave vectors



Rays are:

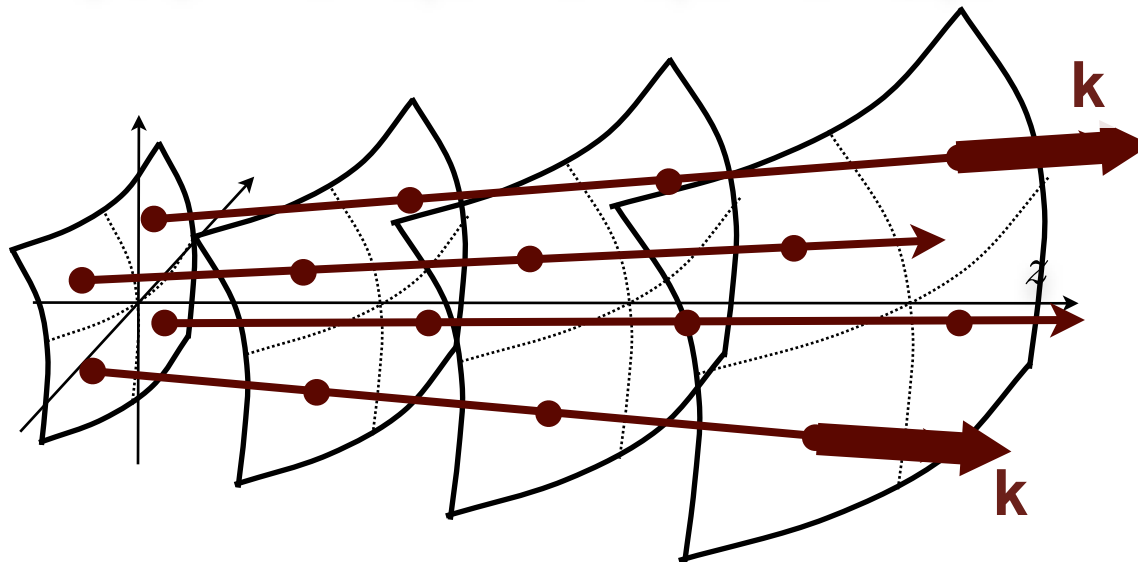
- 1) normals to the wavefront surfaces
- 2) trajectories of “particles of light”

Wave vectors:

At each point on the wavefront, we may assign a normal vector \mathbf{k}

This is known as the wave vector; its magnitude k is the wave number and it is defined as

$$k \equiv |\mathbf{k}| = \frac{2\pi}{\lambda}$$



3D wave vector from the wave equation

We try a sinusoidal solution

$$a \exp \{ i (k_x x + k_y y + k_z z - \omega t) \} =$$

$$= a \exp \{ i (\mathbf{k} \cdot \mathbf{r} - \omega t) \}, \quad \text{where}$$

$\mathbf{k} = \hat{\mathbf{x}}k_x + \hat{\mathbf{y}}k_y + \hat{\mathbf{z}}k_z$ is the wave vector, and

$\mathbf{r} = \hat{\mathbf{x}}x + \hat{\mathbf{y}}y + \hat{\mathbf{z}}z$ is the Cartesian

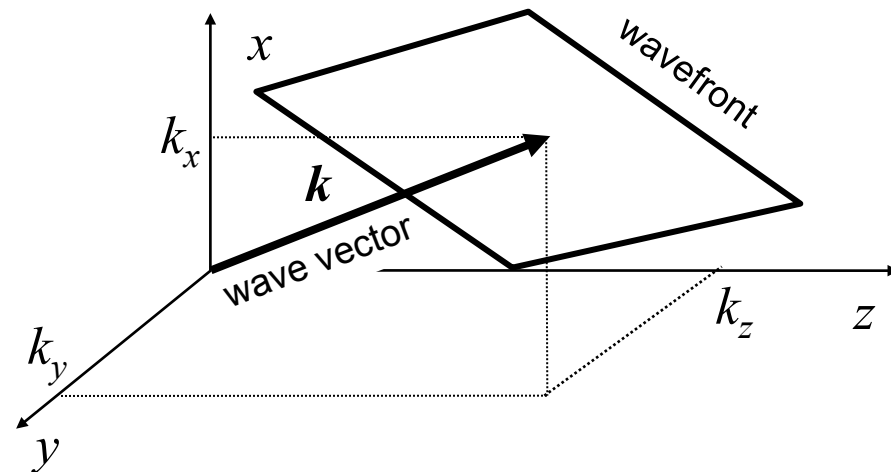
coordinate vector, to the 3D wave equation

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} - \frac{1}{c^2} \frac{\partial^2 f}{\partial t^2} = 0 \Rightarrow$$

$$-a \left(k_x^2 + k_y^2 + k_z^2 - \frac{\omega^2}{c^2} \right) e^{i(k_x x + k_y y + k_z z - \omega t)} = 0 \Rightarrow$$

$$k_x^2 + k_y^2 + k_z^2 = \frac{\omega^2}{c^2}.$$

That is, $|\mathbf{k}| = \frac{\omega}{c} = \frac{2\pi n}{\lambda} \equiv k$ (wave number.)



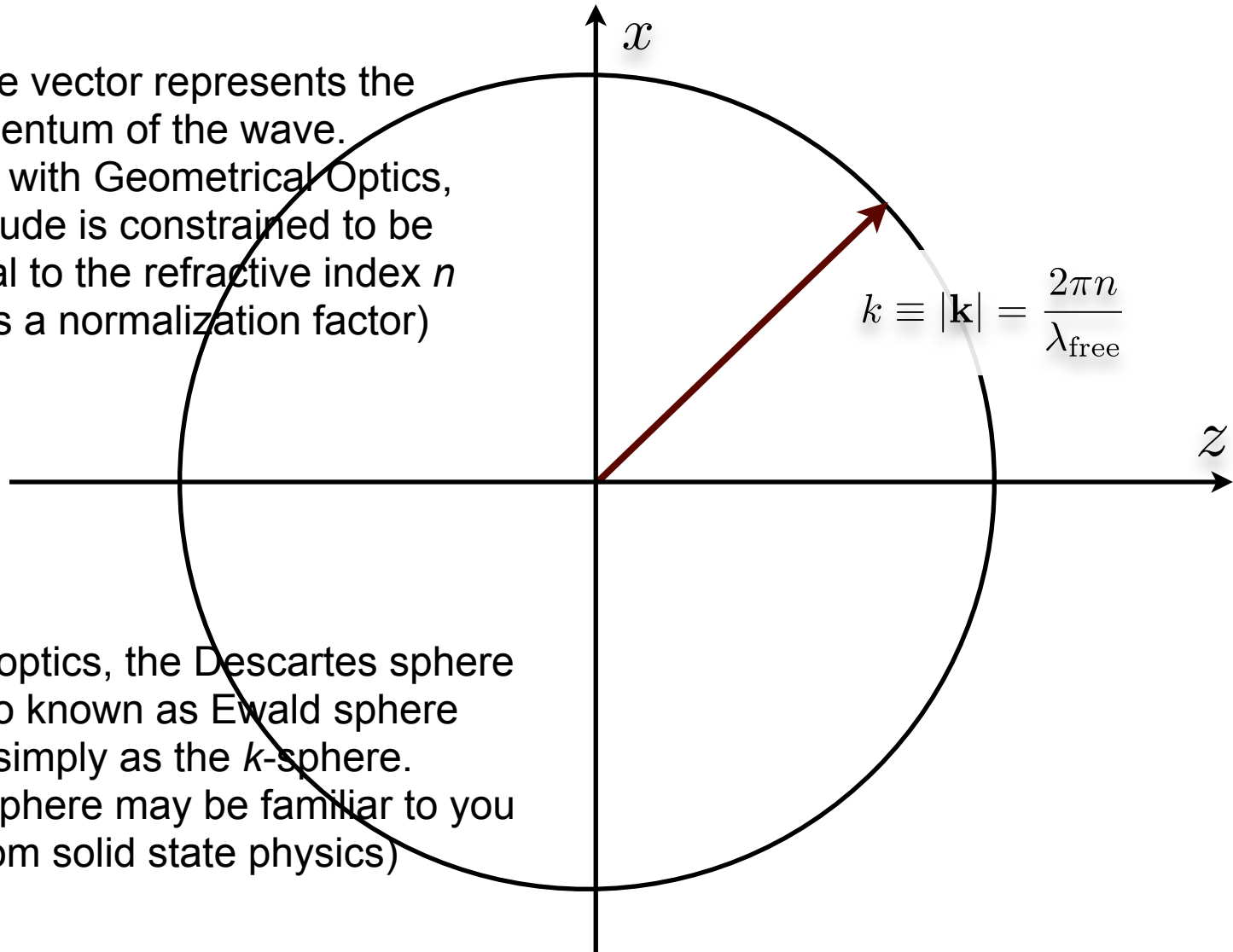
The wavefront is the surface

$$\mathbf{k} \cdot \mathbf{r} = \text{const.}$$

i.e., the locus of points on the wave that have the same phase (modulo 2π) after propagating by the same time t .

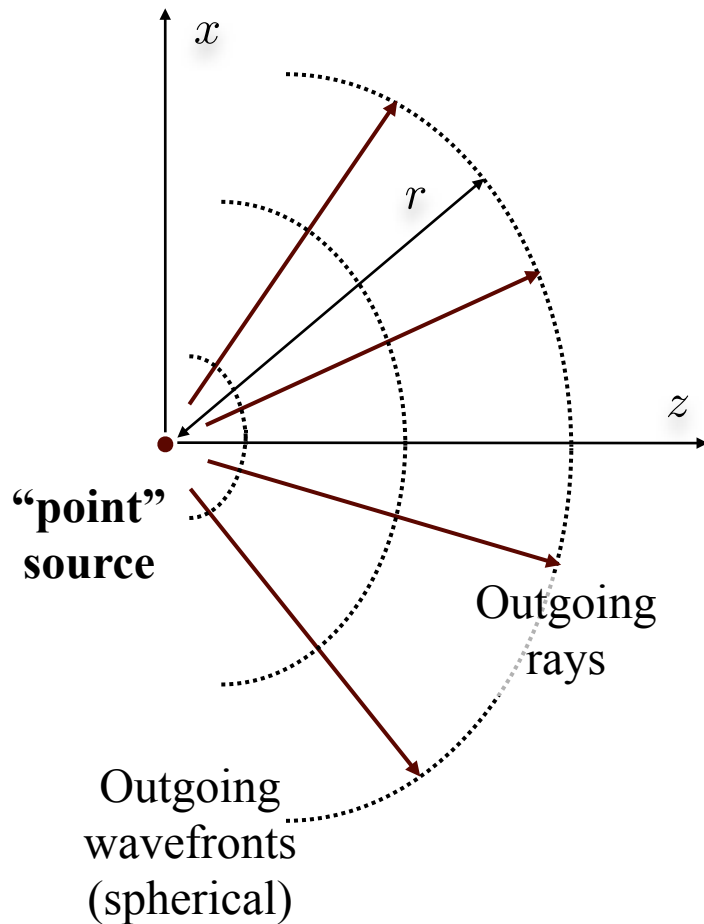
3D wave vector and the Descartes sphere

The wave vector represents the momentum of the wave.
Consistent with Geometrical Optics, its magnitude is constrained to be proportional to the refractive index n ($2\pi/\lambda_{\text{free}}$ is a normalization factor)



In wave optics, the Descartes sphere is also known as Ewald sphere or simply as the k -sphere.
(Ewald sphere may be familiar to you from solid state physics)

Spherical wave



The wavefront in this case is a sphere

$$kr = \text{const.}, \quad \text{where } r \equiv |\mathbf{r}|.$$

Without proof (pls. see the textbook) we assert

$$f(\mathbf{r}, t) = a \frac{\cos(kr - \omega t - \pi/2)}{r}$$

In complex representation,

$$\hat{f}(\mathbf{r}, t) = a \frac{\exp\{i(kr - \omega t)\}}{ir},$$

and in phasor notation (dropping the $e^{-i\omega t}$)

$$\hat{f}(\mathbf{r}) = \frac{a}{ir} \exp\{ikr\}.$$

In the paraxial approximation, $z \gg |x|, |y|$ so

$$r = \sqrt{x^2 + y^2 + z^2} = z \sqrt{1 + \frac{x^2 + y^2}{z^2}} \approx z + \frac{x^2 + y^2}{2z} \Rightarrow$$

$$\begin{aligned} \hat{f}(\mathbf{r}) &\approx \frac{a}{iz} \exp\{ikz\} \exp\left\{ik \frac{x^2 + y^2}{2z}\right\} \\ &= \frac{a}{iz} \exp\left\{i \frac{2\pi}{\lambda} z\right\} \exp\left\{i\pi \frac{x^2 + y^2}{\lambda z}\right\}. \end{aligned}$$

Dispersive waves

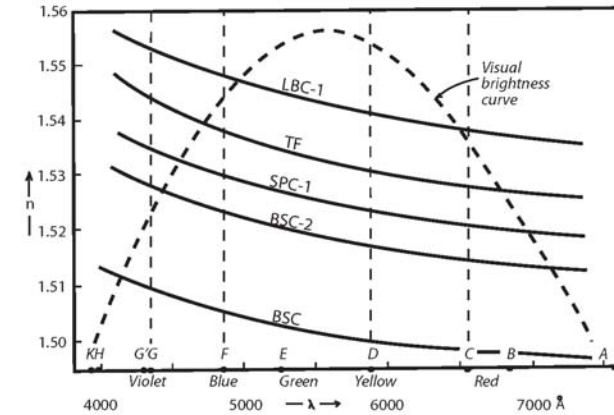
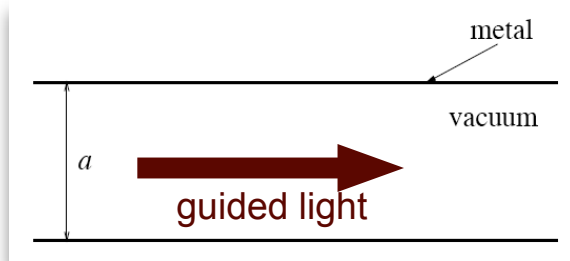
We have learnt from Geometrical Optics that the speed of light can be wavelength dependent, e.g. due to material dispersion $n(\lambda)$. This means that the wave equation for light waves must be written as

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = \frac{1}{c^2(k)} \frac{\partial^2 f}{\partial t^2},$$

where $c(k) = c_{\text{vacuum}}/n(k)$ denotes the dependence of c on the wave number $k = 2\pi/\lambda$. This kind of wave is called **dispersive**.

Another example of a dispersive wave is a **guided wave**. It turns out that, due to the boundary conditions at the waveguide's edge, the simple dispersion relation $c = \lambda\nu$ does **not** hold for a waveguide, and it must be replaced by a different relationship. Without going into the details here, the dispersion relationship for the metal waveguide shown on the left is

$$\left(\frac{m\pi}{a}\right)^2 + k^2 = \left(\frac{\omega}{c}\right)^2, \quad m = 0, \pm 1, \pm 2, \dots$$

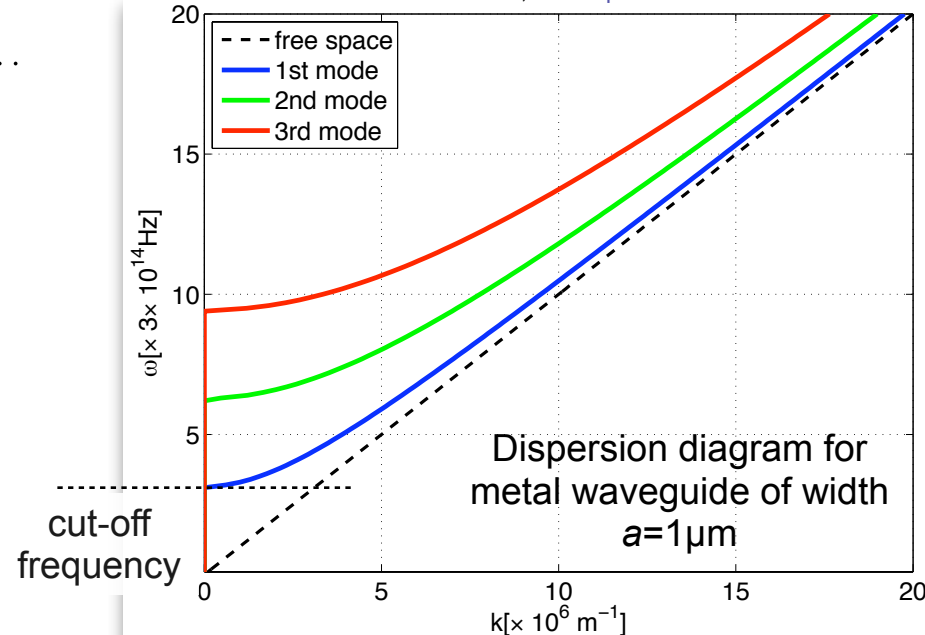


Dispersion curves for glass

Fig. 9X, Y in Jenkins, Francis A., and Harvey E. White. *Fundamentals of Optics*. 4th ed. New York, NY: McGraw-Hill, 1976. ISBN: 9780070323308.

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Superposition of waves at different frequencies

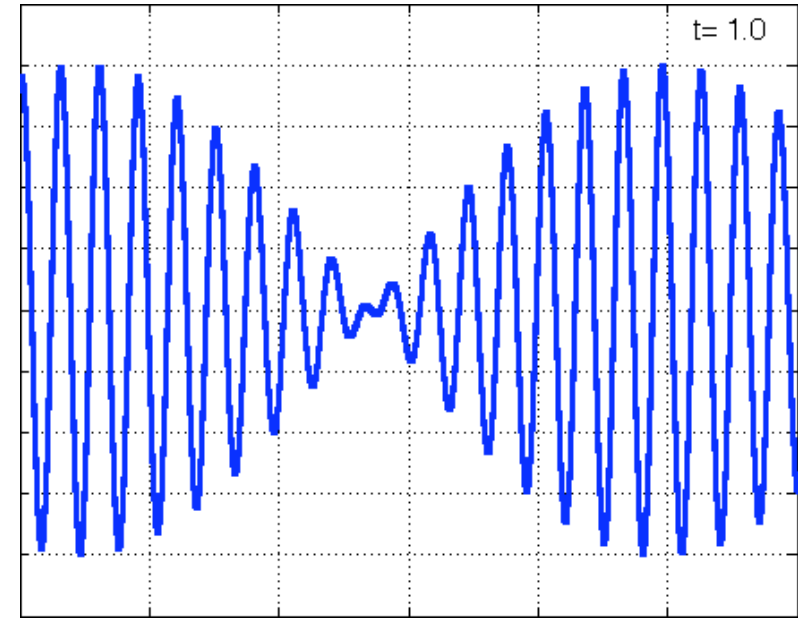
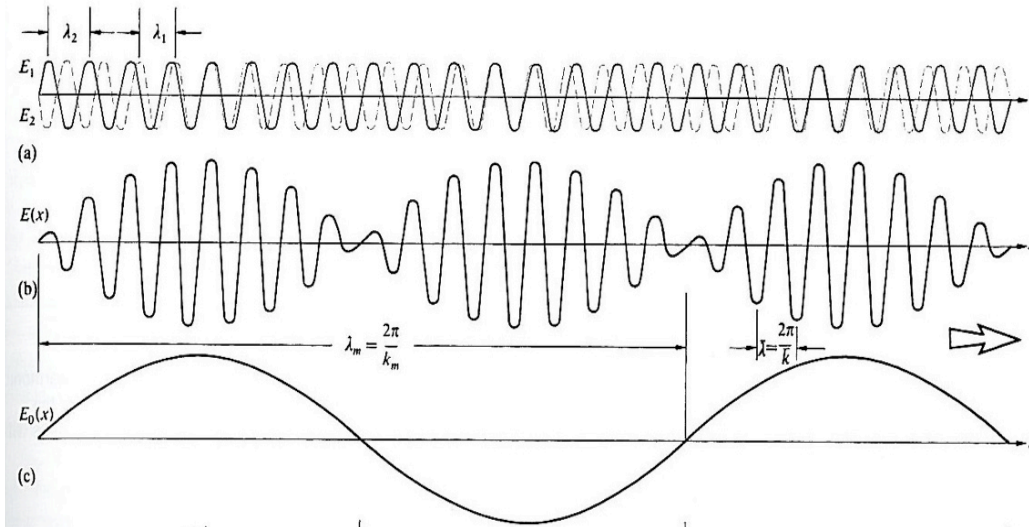


Fig. 7.16a,b,c in Hecht, Eugene. Optics. Reading, MA: Addison-Wesley, 2001. ISBN: 9780805385663. (c) Addison-Wesley. All rights reserved. This content is excluded from our Creative Commons license. For more information, see <http://ocw.mit.edu/fairuse>.

Consider two waves of different frequency and wavelength

$$f_1(z, t) = a \cos(k_1 z - \omega_1 t), \quad f_2(z, t) = a \cos(k_2 z - \omega_2 t).$$

Their superposition is

$$\begin{aligned} f(z, t) &= f_1(z, t) + f_2(z, t) \\ &= a \cos(k_1 z - \omega_1 t) + a \cos(k_2 z - \omega_2 t) \\ &= 2a \cos \frac{(k_1 + k_2) z - (\omega_1 + \omega_2) t}{2} \cos \frac{(k_1 - k_2) z - (\omega_1 - \omega_2) t}{2} \\ &\equiv 2a \cos(k_c z - \omega_c t) \cos(k_m z - \omega_m t), \end{aligned}$$

$$\text{where } k_c \equiv \frac{k_1 + k_2}{2} \quad \text{and} \quad \omega_c \equiv \frac{\omega_1 + \omega_2}{2};$$

are the wave vector and frequency of the **carrier** wave; and

$$k_m \equiv \frac{k_1 - k_2}{2} \quad \text{and} \quad \omega_m \equiv \frac{\omega_1 - \omega_2}{2};$$

are the wave vector and frequency of the **modulation**. \$\omega_m\$ is also referred to as **beat frequency**.

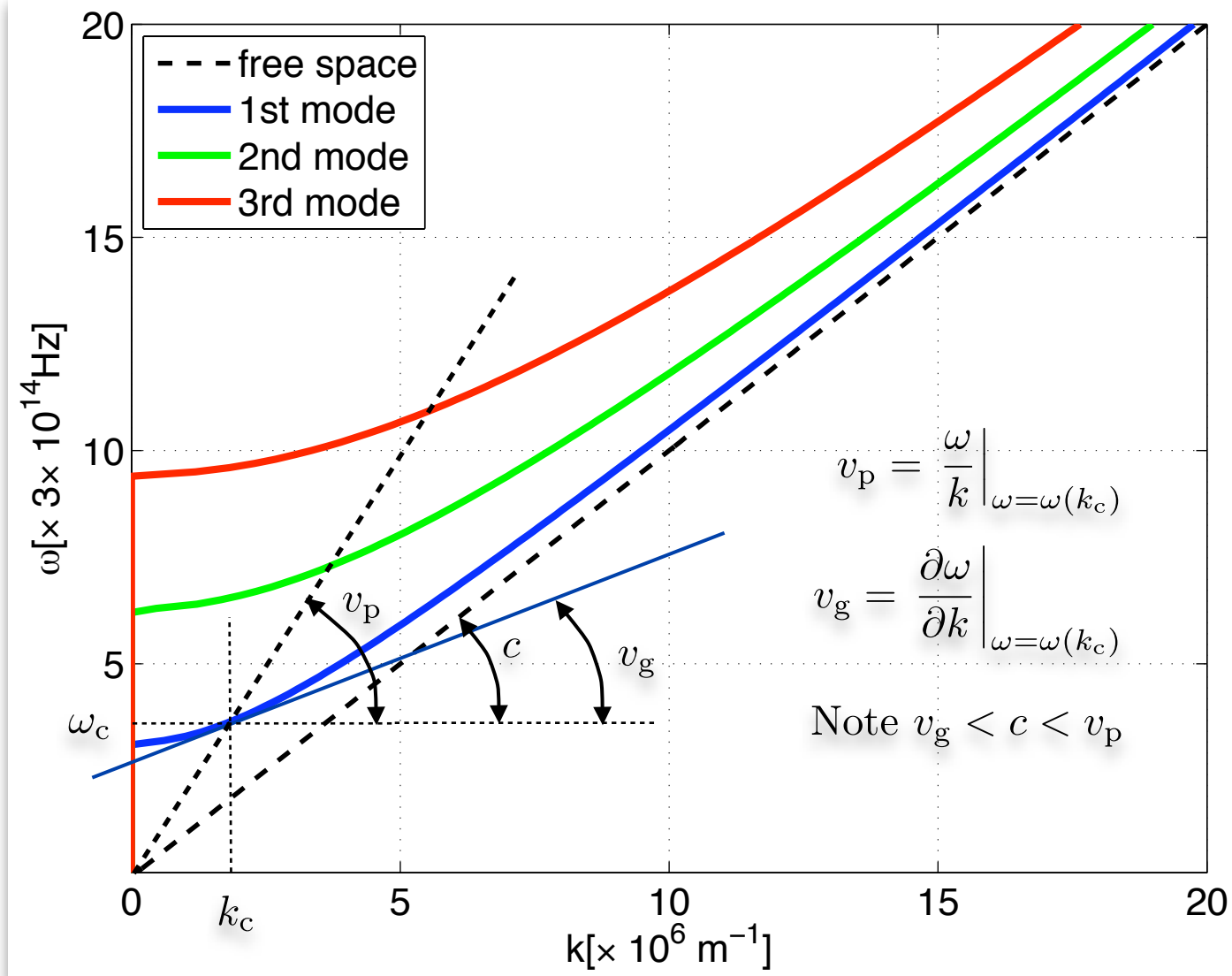
If \$\omega_1 \approx \omega_2\$ and \$k_1 \approx k_2\$, then

$$v_p \equiv \frac{\omega}{k}, \quad \text{and} \quad v_g \equiv \left. \frac{\partial \omega}{\partial k} \right|_{\omega=\omega(k)}.$$

The carrier wave propagates at the **phase velocity** \$v_p \equiv \frac{\omega_c}{k_c}\$,

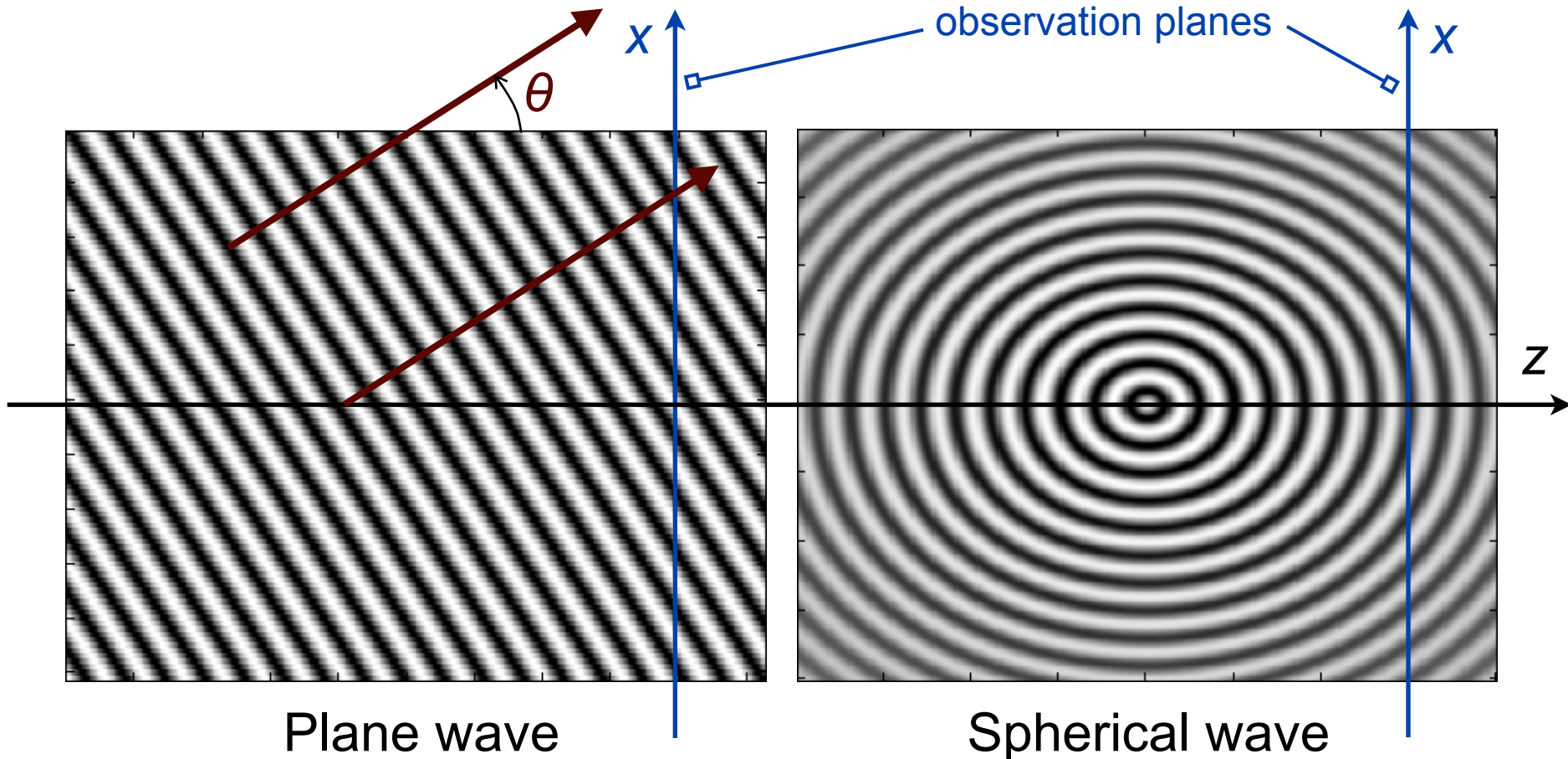
whereas the modulation propagates at the **group velocity** \$v_g \equiv \frac{\omega_m}{k_m}\$.

Group and phase velocity



Spatial frequencies

We now turn to a monochromatic (single color) optical field. The field is often observed (or measured) at a planar surface along the optical axis z . The wavefront shape at the observation plane is, therefore, of particular interest.



Spatial frequencies

$$E(x, z) = \exp \left\{ i \frac{2\pi}{\lambda} (x \sin \theta + z \cos \theta) \right\}$$

$$= \exp \left\{ i 2\pi \left(\frac{x}{\Lambda} + \text{const} \right) \right\}$$

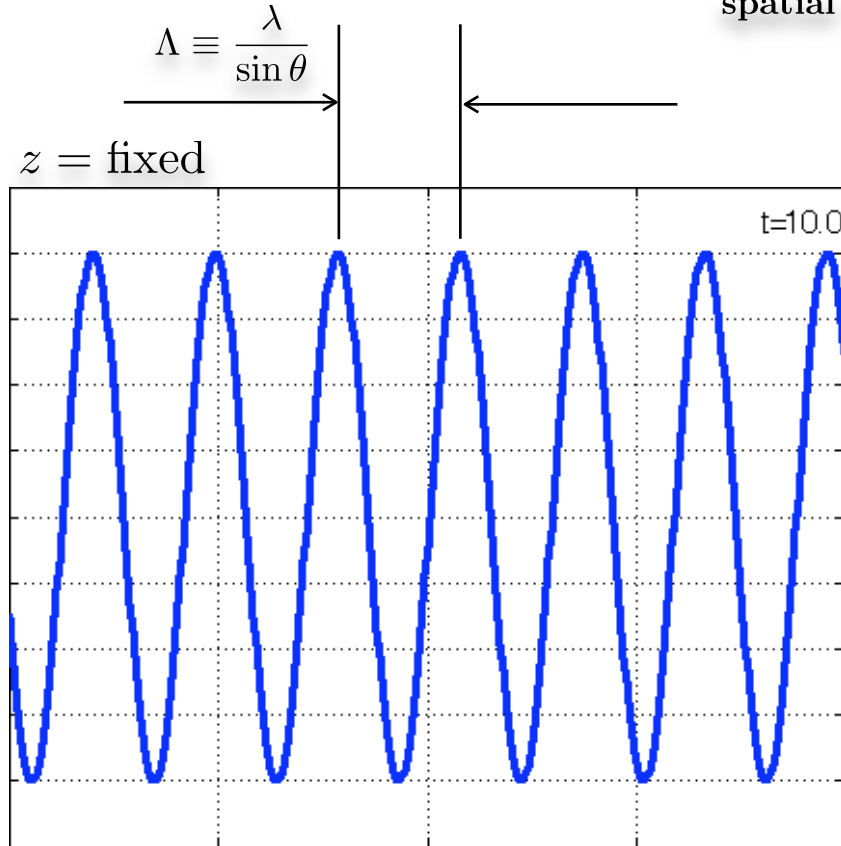
$$f_X \equiv \frac{1}{\Lambda} = \frac{\lambda}{\sin \theta}$$

spatial frequency

$$E(x, z) \sim \exp \left\{ i \frac{2\pi}{\lambda} \sqrt{x^2 + y^2 + z^2} \right\}$$

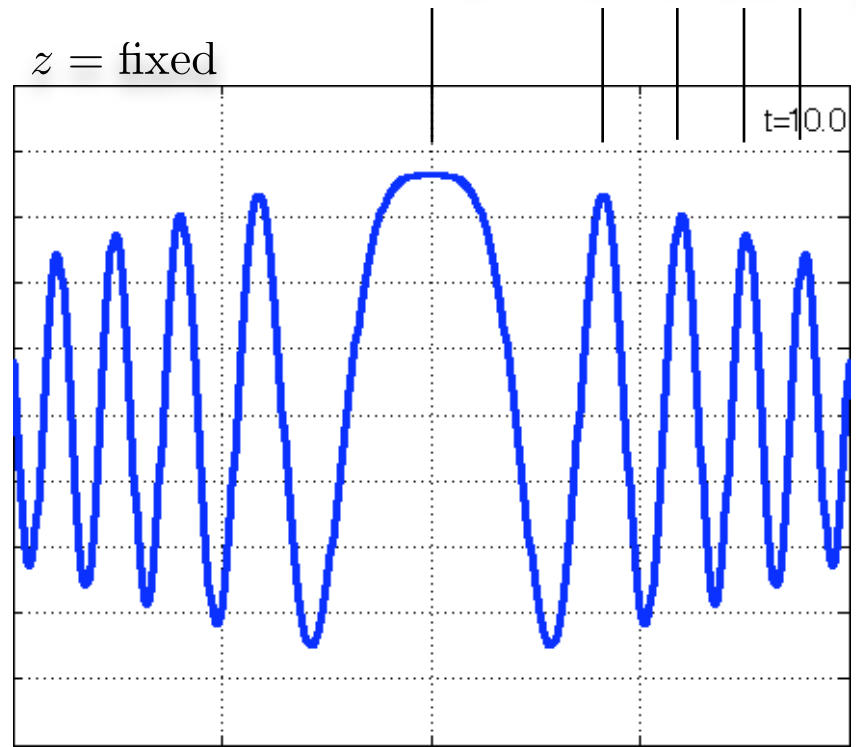
$$\approx \exp \left\{ i \frac{2\pi z}{\lambda} \right\} \exp \left\{ i \pi \frac{x^2 + y^2}{\lambda z} \right\}$$

Chirped frequency $f_X(x) \sim \frac{2x}{\lambda z}$



Plane wave

x



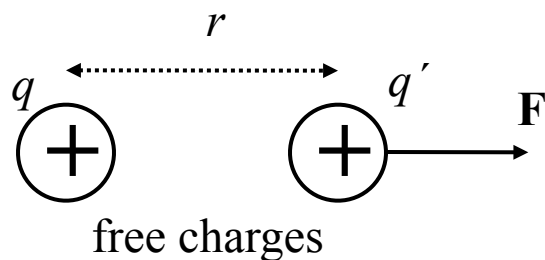
Spherical wave

x

Today

- Electromagnetics
 - Electric (Coulomb) and magnetic forces
 - Gauss Law: electrical
 - Gauss Law: magnetic
 - Faraday's Law
 - Ampère-Maxwell Law
 - Maxwell's equations \Rightarrow Wave equation
 - Energy propagation
 - Poynting vector
 - average Poynting vector: intensity
 - Calculation of the intensity from phasors
 - Intensity

Electric and magnetic forces

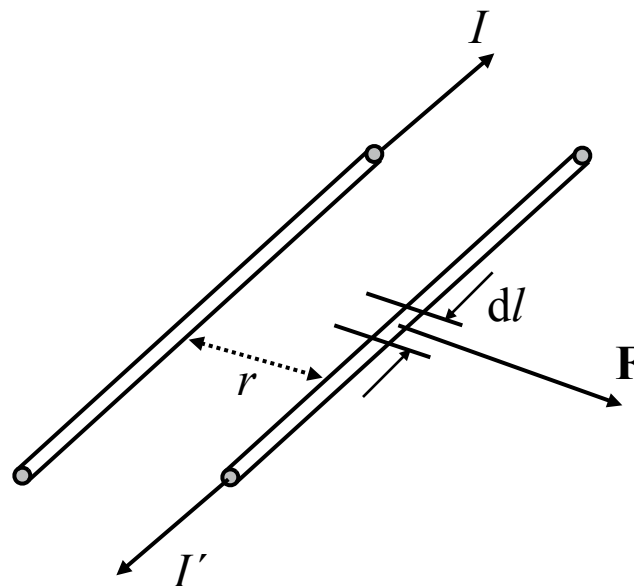


Coulomb force

$$|\mathbf{F}| = \frac{1}{4\pi\epsilon_0} \frac{qq'}{r^2}$$

(dielectric) permittivity
of free space

$$\epsilon_0 = 8.8542 \times 10^{-12} \frac{\text{Cb}^2}{\text{N} \cdot \text{m}^2}$$



Magnetic force

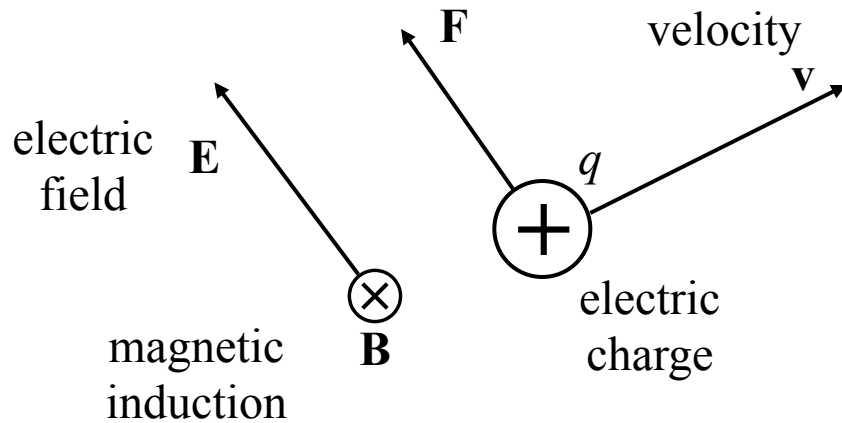
$$\frac{d|\mathbf{F}|}{dl} = \mu_0 \frac{II'}{2\pi r}$$

(magnetic) permeability
of free space

$$\mu_0 = 4\pi \times 10^{-7} \frac{\text{N} \cdot \text{sec}^2}{\text{Cb}^2}$$

Electric and magnetic fields

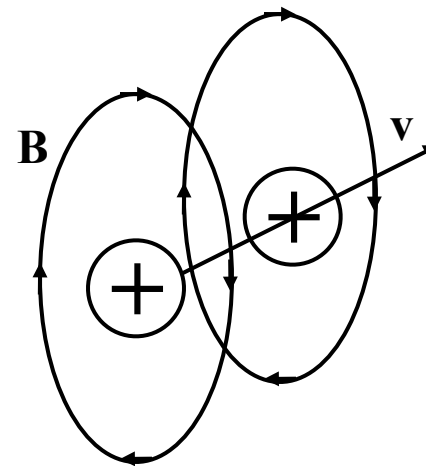
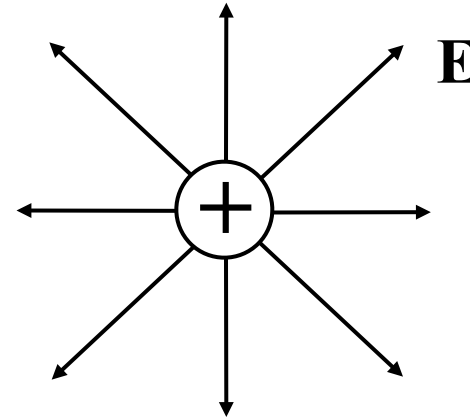
Observation



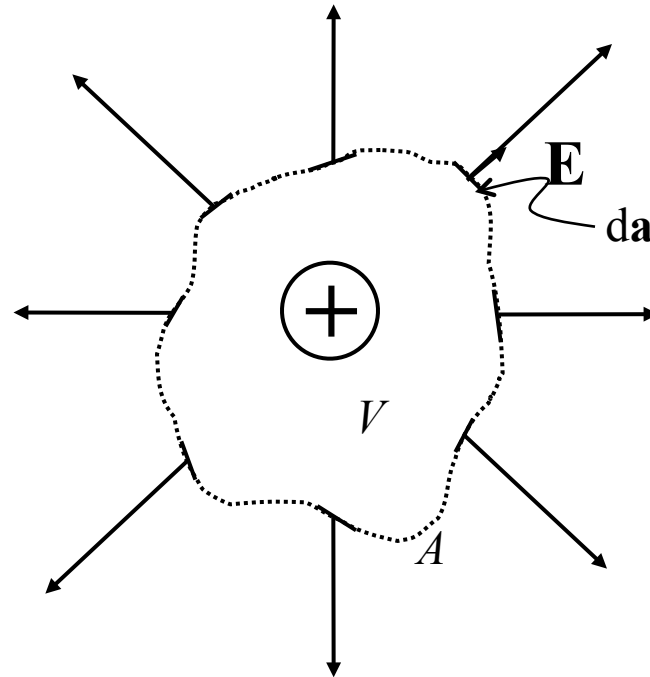
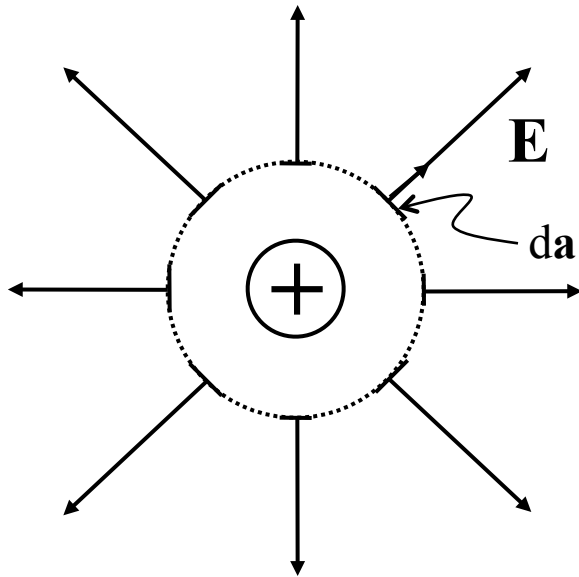
$$\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B})$$

Lorentz force

Generation



Gauss Law: electric field



$$\oiint_A \mathbf{E} \cdot d\mathbf{a} = \frac{1}{\epsilon_0} \iiint_V \rho dV$$

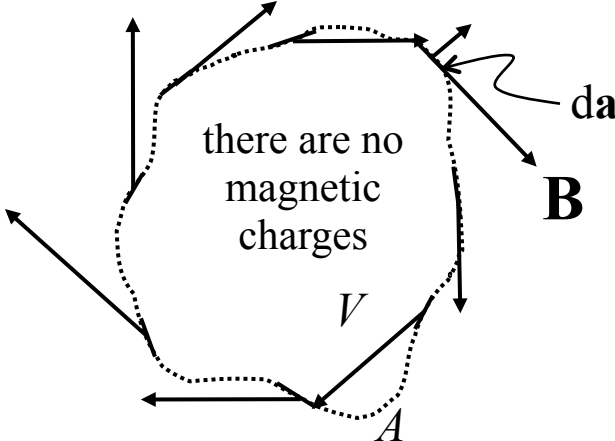
ρ : charge density

Gauss theorem



$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

Gauss Law: magnetic field



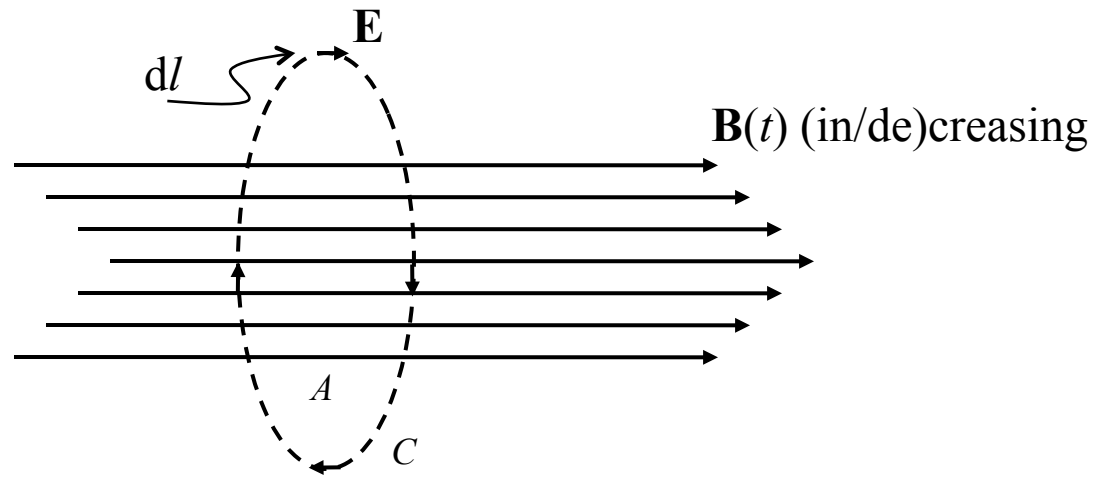
$$\oiint_A \mathbf{B} \cdot d\mathbf{a} = 0$$

Gauss theorem



$$\nabla \cdot \mathbf{B} = 0$$

Faraday's Law: electromotive force



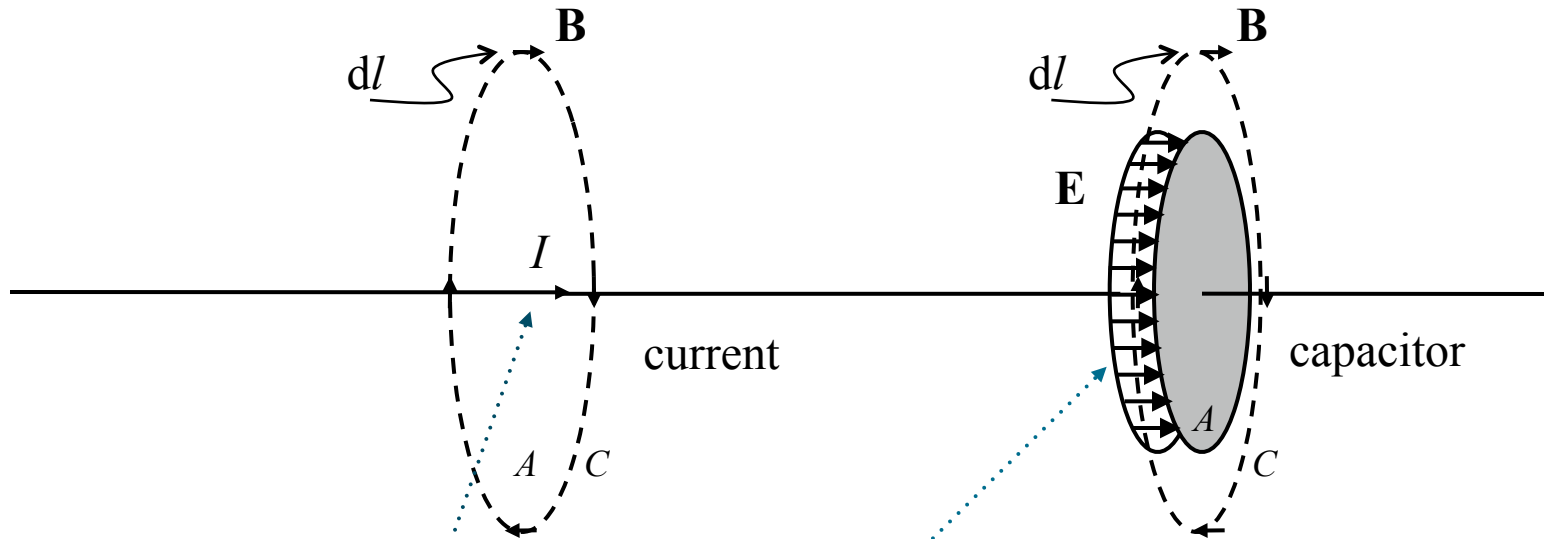
$$\oint_C \mathbf{E} \cdot d\mathbf{l} = -\frac{d}{dt} \iint_A \mathbf{B} \cdot d\mathbf{a}$$

Stokes theorem



$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

Ampère-Maxwell Law: magnetic induction



$$\oint_C \mathbf{B} \cdot d\mathbf{l} = \mu_0 \left(\iint_A \mathbf{J} \cdot d\mathbf{a} + \epsilon_0 \iint_A \frac{\partial \mathbf{E}}{\partial t} \cdot d\mathbf{a} \right) \xleftrightarrow{\text{Stokes theorem}} \nabla \times \mathbf{B} = \mu_0 \left(\mathbf{J} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \right)$$

Maxwell's Equations (free space)

Integral form

$$\oiint_A \mathbf{E} \cdot d\mathbf{a} = \frac{1}{\epsilon_0} \iiint_V \rho dV$$

$$\oiint_A \mathbf{B} \cdot d\mathbf{a} = 0$$

$$\oint_C \mathbf{E} \cdot d\mathbf{l} = -\frac{d}{dt} \iint_A \mathbf{B} \cdot d\mathbf{a}$$

$$\oint_C \mathbf{B} \cdot d\mathbf{l} = \mu_0 \left(\iint_A \mathbf{J} \cdot d\mathbf{a} + \epsilon_0 \iint_A \frac{\partial \mathbf{E}}{\partial t} \cdot d\mathbf{a} \right)$$

Differential form

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \times \mathbf{B} = \mu_0 \left(\mathbf{J} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \right)$$

Wave Equation for electromagnetic waves

We will derive the Wave Equation from Maxwell's electromagnetic equations in free space and in the absence of charges and currents.

Starting from Faraday's equation,

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \Rightarrow \nabla \times (\nabla \times \mathbf{E}) = -\frac{\partial (\nabla \times \mathbf{B})}{\partial t}$$

Now we substitute Ampère–Maxwell's Law

$$\nabla \times \mathbf{B} = \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t},$$

the following identity from vector calculus

$$\nabla \times (\nabla \times \mathbf{E}) = \nabla (\nabla \cdot \mathbf{E}) - \nabla^2 \mathbf{E},$$

and Gauss' Law for electric fields,

$$\nabla \cdot \mathbf{E} = 0.$$

Collecting all these results, we obtain

$$\nabla^2 \mathbf{E} - \mu_0 \epsilon_0 \frac{\partial^2 \mathbf{E}}{\partial t^2} = 0.$$

Comparing with the 3D Wave Equation,

$$\nabla^2 f - \frac{1}{c^2} \frac{\partial^2 f}{\partial t^2} = 0,$$

we see that *each component* of the vector \mathbf{E} satisfies the Wave Equation with velocity

$$\frac{1}{c^2} = \mu_0 \epsilon_0 \Rightarrow c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

Since $\epsilon_0 = 8.8542 \times 10^{-12} \text{Cb}^2/\text{N} \cdot \text{m}^2$,
 $\mu_0 = 4\pi \times 10^{-7} \text{N} \cdot \text{sec}^2/\text{Cb}^2$, we obtain
the speed of electromagnetic waves in vacuum

$$c = 3 \times 10^8 \frac{\text{m}}{\text{sec}}.$$

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