Problem Set 4

Please write your solutions in the LATEX and Python templates provided. Aim for concise solutions; convoluted and obtuse descriptions might receive low marks, even when they are correct.

Problem 4-1. [10 points] Binary Tree Practice

(a) [2 points] The Set Binary Tree T below is **not height-balanced** but does satisfy the **binary search tree** property, assuming the key of each integer item is itself. Indicate the keys of all nodes that are not height-balanced and compute their skew.



- (b) [5 points] Perform the following insertions and deletions, one after another in sequence on T, by adding or removing a leaf while maintaining the binary search tree property (a key may need to be swapped down into a leaf). For this part, **do not** use rotations to balance the tree. Draw the modified tree after each operation.
 - 1 T.insert(2)
 - 2 T.delete(49)
 - 3 T.delete(35)
 - 4 T.insert(85)
 - 5 T.delete(84)
- (c) [3 points] For each unbalanced node identified in part (a), draw the two trees that result from rotating the node in the **original** tree left and right (when possible). For each tree drawn, specify whether it is height-balanced, i.e., all nodes satisfy the AVL property.

Note: Material on this page requires material that will be covered in **L08 on March 3, 2020**. We suggest waiting to solve these problem until after that lecture. All other pages of this assignment can be solved using only material from L07 and earlier.

Problem 4-2. Heap Practice [10 points]

For each array below, draw it as a **complete**¹ binary tree and state whether the tree is a max-heap, a min-heap, or neither. If the tree is neither, turn the tree into a min-heap by repeatedly swapping items that are **adjacent in the tree**. Communicate your swaps by drawing a sequence of trees, marking on each tree the pair that was swapped.

(a) [4, 12, 8, 21, 14, 9, 17]
(b) [701, 253, 24, 229, 17, 22]
(c) [2, 9, 13, 8, 0, 2]
(d) [1, 3, 6, 5, 4, 9, 7]

Problem 4-3. [10 points] Gardening Contest

Gardening company Wonder-Grow sponsors a nation-wide gardening contest each year where they rate gardens around the country with a positive integer² *score*. A garden is designated by a *garden pair* (s_i, r_i) , where s_i is the garden's assigned score and r_i is the garden's unique positive integer *registration number*.

- (a) [5 points] To support inclusion and reduce competition, Wonder-Grow wants to award identical trophies to the top k gardens. Given an unsorted array A of garden pairs and a positive integer $k \le |A|$, describe an $O(|A| + k \log |A|)$ -time algorithm to return the registration numbers of k gardens in A with highest scores, breaking ties arbitrarily.
- (b) [5 points] Wonder-Grow decides to be more objective and award a trophy to every garden receiving a score strictly greater than a reference score x. Given a max-heap A of garden pairs, describe an $O(n_x)$ -time algorithm to return the registration numbers of all gardens with score larger than x, where n_x is the number of gardens returned.

¹Recall from Lecture 8 that a binary tree is *complete* if it has exactly 2^i nodes of depth *i* for all *i* except possibly the largest, and at the largest depth, all nodes are as far left as possible.

²In this class, when an integer or string appears in an input, without listing an explicit bound on its size, you should assume that it is provided inside a constant number of machine words in the input.

Problem 4-4. [15 points] Solar Supply

Entrepreneur Bonty Murns owns a set S of n solar farms in the town of Fallmeadow. Each solar farm $(s_i, c_i) \in S$ is designated by a unique positive integer *address* s_i and a farm *capacity* c_i : a positive integer corresponding to the maximum energy production rate the farm can support. Many buildings in Fallmeadow want power. A building (b_j, d_j) is designated by a unique *name* string b_j and a *demand* d_j : a positive integer corresponding to the building's energy consumption rate.

To receive power, a building in Fallmeadow must be connected to a **single** solar farm under the restriction that, for any solar farm s_i , the sum of demand from all the buildings connected to s_i may not exceed the farm's capacity c_i . Describe a database supporting the following operations, and for each operation, specify whether your running time is worst-case, expected, and/or amortized.

initialize(S)	Initialize database with a list $S = ((s_0, c_0), \dots, (s_{n-1}, c_{n-1}))$
	corresponding to n solar farms in $O(n)$ time.
power_on(b_j , d_j)	Connect a building with name b_j and demand d_j to any
	solar farm having available capacity at least d_j in $O(\log n)$ time
	(or return that no such solar farm exists).
power_off(b_j)	Remove power from the building with name b_j in $O(\log n)$ time.
customers (s_i)	Return the names of all buildings supplied by the farm at address s_i
	in $O(k)$ time, where k is the number of building names returned.

Problem 4-5. [15 points] Robot Wrangling

Dr. Squid has built a robotic arm from n+1 rigid bars called *links*, each connected to the one before it with a rotating joint (n joints in total). Following standard practice in robotics³, the orientation of each link is specified locally relative to the orientation of the previous link. In mathematical notation, the change in orientation at a joint can be specified using a 4×4 *transformation matrix*. Let $\mathcal{M} = (M_0, \ldots, M_{n-1})$ be an array of transformation matrices associated with the arm, where matrix M_k is the change in orientation at joint k, between links k and k + 1.

To compute the position of the *end effector*⁴, Dr. Squid will need the arm's *full transformation*: the ordered matrix product of the arm's transformation matrices, $\prod_{k=0}^{n-1} M_k = M_0 \cdot M_1 \cdot \ldots \cdot M_{n-1}$. Assume Dr. Squid has a function matrix_multiply (M_1, M_2) that returns the matrix product⁵ $M_1 \times M_2$ of any two 4×4 transformation matrices in O(1) time. While tinkering with the arm changing one joint at a time, Dr. Squid will need to re-evaluate this matrix product quickly. Describe a database to support the following **worst-case** operations to accelerate Dr. Squid's workflow:

initialize($\mathcal M$)	Initialize from an initial input configuration \mathcal{M} in $O(n)$ time.
update_joint(k , M)	Replace joint k's matrix M_k with matrix M in $O(\log n)$ time.
<pre>full_transformation()</pre>	Return the arm's current full transformation in $O(1)$ time.

³More on forward kinematic robotics computation here: <u>https://en.wikipedia.org/wiki/Forward_kinematics</u>

⁴i.e., the device at the end of a robotic arm: <u>https://en.wikipedia.org/wiki/Robot_end_effector</u>

⁵Recall, matrix multiplication is not commutative, i.e., $M_1 \cdot M_2 \neq M_2 \cdot M_1$, except in very special circumstances.

Problem 4-6. [40 points] $\pi z^2 a$ Optimization

Liza Pover has found a Monominos pizza left over from some big-TEX recruiting event. The pizza is a disc⁶ with radius z, having n toppings labeled $0, \ldots, n-1$. Assume z fits in a single machine word, so integer arithmetic on O(1) such integers can be done in O(1) time. Each topping i:

- is located at Cartesian coordinates (x_i, y_i) where x_i, y_i are integers from range $R = \{-z, \dots, z\}$ (you may assume that **all coordinates are distinct**), and
- has integer *tastiness* $t_i \in R$ (note, topping tastiness can be negative, e.g., if it's pineapple⁷).

Liza wants to pick a point (x', y') and make a pair of cuts from that point, one going straight down and one going straight left, and take the resulting *slice*, i.e., the intersection of the pizza with the two half-planes $x \le x'$ and $y \le y'$. The tastiness of this slice is the sum of all t_i such that $x_i \le x'$ and $y_i \le y'$. Liza wants to find a *tastiest* slice, that is, a slice of maximum tastiness. Assume there exists a slice with **positive tastiness**.

- (a) [2 points] If point (x', y') results in a slice with tastiness $t \neq 0$, show there exists $i, j \in \{0, 1, \ldots, n-1\}$ such that point (x_i, y_j) results in a slice of equal tastiness t (i.e., a tastiest slice exists resulting from a point that is both vertically and horizontally aligned with toppings).
- (b) [8 points] To make finding a tastiest slice easier, show how to modify a Set AVL Tree so that:
 - it stores **key-value items**, where each item x contains a value x.val (in addition to its key x.key on which the Set AVL is ordered);
 - it supports a new tree-level operation $\max \text{prefix}()$ which returns in worstcase O(1) time a pair $(k^*, \text{prefix}(k^*))$, where k^* is any key stored in the tree T that maximizes the *prefix sum*, $\text{prefix}(k) = \{x. v \ge l \mid x \in T \text{ and } x. key \le k\}$ (that is, the sum of all values of items whose keys are $\le k$); and
 - all other Set AVL Tree operations maintain their running times.
- (c) [5 points] Using the data structure from part (b) as a black box, describe a **worst-case** $O(n \log n)$ -time algorithm to return a triple (x, y, t), where point (x, y) corresponds to a slice of maximum tastiness t.
- (d) [25 points] Write a Python function tastiest_slice(toppings) that implements your algorithm from part (c), including an implementation of your data structure from part (b).

⁶The pizza has thickness a, so it has volume $\pi z^2 a$.

⁷If you believe that Liza's <u>Pizza</u> preferences are objectively wrong, feel free to assert your opinions on <u>Piazza</u>.

```
1 from Set_AVL_Tree import BST_Node, Set_AVL_Tree
3 class Key_Val_Item:
      def __init__(self, key, val):
4
          self.key = key
5
          self.val = val
6
     def __str__(self):
8
          return "%s,%s" % (self.key, self.val)
9
11 class Part_B_Node(BST_Node):
      def subtree_update(A):
          super().subtree update()
          ****
14
          # ADD ANY NEW SUBTREE AUGMENTATION HERE #
          16
  class Part_B_Tree(Set_AVL_Tree):
18
      def __init__(self):
19
          super().__init__(Part_B_Node)
      def max_prefix(self):
          ...
          Output: (k, s) | a key k stored in tree whose
24
                        | prefix sum s is maximum
          ...
2.6
          k, s = 0, 0
          #######################
28
          # YOUR CODE HERE #
29
          ########################
          return (k, s)
  def tastiest_slice(toppings):
      ...
34
      Input: toppings | List of integer tuples (x,y,t) representing
                       | a topping at (x, y) with tastiness t
36
      Output: tastiest | Tuple (X,Y,T) representing a tastiest slice
                       | at (X,Y) with tastiness T
38
      ...
39
      B = Part B Tree()
                          # use data structure from part (b)
40
      X, Y, T = 0, 0, 0
41
      ########################
42
      # YOUR CODE HERE #
43
      ######################
44
45
      return (X, Y, T)
```

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