

## ES.1803 Quiz 4 Solutions, Spring 2024

**Problem 1.** (20 points)

Let  $A = \begin{bmatrix} 1 & 2 & 1 & 3 \\ 1 & 2 & 3 & 7 \\ 2 & 4 & 6 & 14 \end{bmatrix}$

(a) (10) *Put  $A$  in reduced row echelon form.*

**Solution:**  $\begin{bmatrix} 1 & 2 & 1 & 3 \\ 1 & 2 & 3 & 7 \\ 2 & 4 & 6 & 14 \end{bmatrix} \xrightarrow[\text{Row}_3 - 2\text{Row}_1]{\text{Row}_2 - \text{Row}_1} \begin{bmatrix} 1 & 2 & 1 & 3 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 4 & 8 \end{bmatrix} \xrightarrow{\text{Row}_3 - 2\text{Row}_2} \begin{bmatrix} 1 & 2 & 1 & 3 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\text{Row}_2/2}$

$$\begin{bmatrix} 1 & 2 & 1 & 3 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\text{Row}_1 - \text{Row}_2} \boxed{\begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}}.$$

(b) (5) *Give a basis for the column space of  $A$ .*

**Solution:** The pivot columns are Columns 1 and 3. These columns of  $A$  give a basis for

the column space:  $\boxed{\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 6 \end{bmatrix}}.$

(c) (3) *What is the dimension of  $\text{Null}(A)$ ?*

**Solution:** Dimension of  $\text{Null}(A)$  = number of free variables = 2.

(d) (2) *What is the rank of  $A$ ?*

**Solution:** There are two pivots, so the rank is 2.

**Problem 2.** (20 points)

The matrix  $R$  is in reduced row echelon form:  $R = \begin{bmatrix} 1 & -3 & 0 & 3 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$

(a) (10) *Give the general solution to the equation  $R\mathbf{x} = \begin{bmatrix} 3 \\ 4 \\ 0 \\ 0 \end{bmatrix}.$*

**Solution:** We need  $\text{Null}(R)$ , i.e., the general homogeneous solution. As usual, we format the solution by putting the variables below the matrix. The free variables are  $x_2$  and  $x_4$ .

In turn, we set one to 1 and the other to 0 and solve for the pivot variables.

$$\begin{bmatrix} 1 & -3 & 0 & 3 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{array}{cccc} x_1 & x_2 & x_3 & x_4 \\ 3 & 1 & 0 & 0 \\ -3 & 0 & -2 & 1 \end{array}$$

So a basis of  $\text{Null}(R)$  is  $\left\{ \begin{bmatrix} 3 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ -2 \\ 1 \end{bmatrix} \right\}$ .

Since  $R$  is in RREF, it is easy to see that  $\begin{bmatrix} 3 \\ 4 \\ 0 \\ 0 \end{bmatrix} = 3 \cdot \text{Col}_1 + 4 \cdot \text{Col}_3$ . So a particular solution

is  $\mathbf{x}_p = \begin{bmatrix} 3 \\ 0 \\ 4 \\ 0 \end{bmatrix}$ . The general solution is  $\mathbf{x} = \mathbf{x}_p + \mathbf{x}_h = \begin{bmatrix} 3 \\ 0 \\ 4 \\ 0 \end{bmatrix} + c_1 \begin{bmatrix} 3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} -3 \\ 0 \\ -2 \\ 1 \end{bmatrix}$ .

(b) (10) Find a matrix  $A$  with reduced row echelon form  $R$  and such that the equations

$A\mathbf{x} = \begin{bmatrix} 2 \\ 1 \\ 4 \\ 1 \end{bmatrix}$  and  $A\mathbf{x} = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}$  can both be solved.

**Solution:** We put  $\begin{bmatrix} 2 \\ 1 \\ 4 \\ 1 \end{bmatrix}$  and  $\begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}$  as pivot columns of  $A$  and give the free columns the same relations to the pivot columns as seen in  $R$ .

That is  $\text{Col}_2 = -3\text{Col}_1$  and  $\text{Col}_4 = 3 \cdot \text{Col}_1 + 2 \cdot \text{Col}_3$ :

$$A = \begin{bmatrix} 2 & -6 & 1 & 8 \\ 1 & -3 & -1 & 1 \\ 4 & -12 & 0 & 12 \\ 1 & -3 & 0 & 3 \end{bmatrix}$$

**Problem 3.** (30 points)

(a) (10) Let  $A = \begin{bmatrix} 6 & -2 \\ 2 & 1 \end{bmatrix}$ . Find the general real-valued solution to  $\mathbf{x}' = A\mathbf{x}$ .

*Helpful check: Your eigenvalues should be integers.*

**Solution:** Characteristic equation:  $\det \begin{bmatrix} 6 - \lambda & -2 \\ 2 & 1 - \lambda \end{bmatrix} = \lambda^2 - 7\lambda + 10 = 0$ . So,  $\lambda = 2, 5$ .

Basic eigenvectors: Need basis of  $\text{Null}(A - \lambda I)$

For  $\lambda = 2$ :  $A - 2I = \begin{bmatrix} 4 & -2 \\ 2 & -1 \end{bmatrix}$ . Take  $\mathbf{v} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ .

For  $\lambda = 5$ :  $A - 5I = \begin{bmatrix} 1 & -2 \\ 2 & -4 \end{bmatrix}$ . Take  $\mathbf{v} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ .

General (real-valued) solution:  $\mathbf{x} = c_1 e^{2t} \begin{bmatrix} 1 \\ 2 \end{bmatrix} + c_2 e^{5t} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ .

Note: There are many possible ways to give the answer depending on how you chose your eigenvectors.

(b) (10) Suppose  $B$  is a  $3 \times 3$  matrix with eigenvalues 3, 7, 10 and corresponding eigenvectors

$$\begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix}, \quad \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \quad \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}.$$

(i) Find  $\det(B)$ .      (ii) Find  $B \left( 2 \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix} + 4 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right)$ .      (iii) Find  $B^{-1} \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix}$ .

(iv) Give the general solution to the system of DEs  $\mathbf{x}' = B^2 \mathbf{x}$ .

**Solution:** (i)  $\det(B)$  is the product of the eigenvalues = 210.

(ii) Since the vector being multiplied is a linear combination of eigenvectors, the result is

$$B \left( 2 \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix} + 4 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right) = 6 \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix} + 40 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 64 \\ 46 \end{bmatrix}.$$

(iii) Since  $\begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix}$  is an eigenvector with eigenvalue 3 we have  $B^{-1} \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix}$ .

(iv) The eigenvalues of  $B^2$  are  $3^2, 7^2, 10^2$ . The eigenvectors are the same as for  $B$ . So the

general solution is  $\mathbf{x} = c_1 e^{9t} \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix} + c_2 e^{49t} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + c_3 e^{100t} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ .

(c) (5) Give the diagonalized form of the matrix  $B$  from Part (b). That is, write it as a product of certain matrices. You do not have to find inverses explicitly.

**Solution:** We know  $B = S\Lambda S^{-1}$ , where  $S = \begin{bmatrix} 1 & 1 & 0 \\ 4 & -1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$  is the matrix of eigenvectors and

$\Lambda = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 7 & 0 \\ 0 & 0 & 10 \end{bmatrix}$  is the diagonal matrix of eigenvalues. So,

$$B = S\Lambda S^{-1} = \begin{bmatrix} 1 & 1 & 0 \\ 4 & -1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 3 & 0 & 0 \\ 0 & 7 & 0 \\ 0 & 0 & 10 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 4 & -1 & 1 \\ 1 & 1 & 1 \end{bmatrix}^{-1}$$

(d) (5) Suppose  $D$  is a  $2 \times 2$  matrix with eigenvalues  $1 + 2i$  and  $1 - 2i$  and corresponding eigenvectors  $\begin{bmatrix} 1 \\ 3i \end{bmatrix}$  and  $\begin{bmatrix} 1 \\ -3i \end{bmatrix}$ .

Give the general real-valued solution to the equation  $\mathbf{x}' = D\mathbf{x}$ .

**Solution:** One complex solution is  $\mathbf{z}(t) = e^{(1+2i)t} \begin{bmatrix} 1 \\ 3i \end{bmatrix}$ . So,

$$\mathbf{z}(t) = e^t(\cos(2t) + i \sin(2t)) \begin{bmatrix} 1 \\ 3i \end{bmatrix} = e^t \begin{bmatrix} \cos(2t) \\ -3 \sin(2t) \end{bmatrix} + ie^t \begin{bmatrix} \sin(2t) \\ 3 \cos(2t) \end{bmatrix}$$

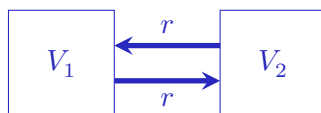
The real and imaginary parts of  $\mathbf{z}$  are both solutions to the DE. So,

$$\mathbf{x}_1(t) = \operatorname{Re}(\mathbf{z}) = e^t \begin{bmatrix} \cos(2t) \\ -3 \sin(2t) \end{bmatrix} \quad \text{and} \quad \mathbf{x}_2(t) = \operatorname{Im}(\mathbf{z}) = e^t \begin{bmatrix} \sin(2t) \\ 3 \cos(2t) \end{bmatrix}$$

are solutions. The general real-valued solution is  $\boxed{\mathbf{x} = c_1 \mathbf{x}_1 + c_2 \mathbf{x}_2}$ .

**Problem 4.** (10 points)

Consider the closed two-compartment mixing tank system shown. Let  $x, y$  be the amount of salt in tanks 1, 2 respectively. The volumes  $V_1, V_2$  and the flow rate  $r$  are (positive) constants.



Assume compatible units and write down in matrix form the system of DEs governing the amount of salt in the tanks.

**Solution:**

$$\begin{aligned} x' &= \text{rate in} - \text{rate out} = r \cdot \frac{y}{V_2} - r \cdot \frac{x}{V_1} \\ y' &= \text{rate in} - \text{rate out} = r \cdot \frac{x}{V_1} - r \cdot \frac{y}{V_2} \end{aligned}$$

In matrix form this is  $\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} -\frac{r}{V_1} & \frac{r}{V_2} \\ \frac{r}{V_1} & -\frac{r}{V_2} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$ .

**Problem 5.** (20 points)

Give a short explanation for each answer.

(a) (4) Suppose  $A$  is a square matrix with RREF  $R$ . True or false:  $A$  and  $R$  have the same eigenvalues.

**Solution:**  $\boxed{\text{False}}$ . For example,  $A = \begin{bmatrix} 6 & 5 \\ 1 & 2 \end{bmatrix}$  has eigenvalues 1, 7. Its RREF is  $I$ , which has eigenvalues 1, 1.

(b) (4) Find the companion system to the DE  $x'' + 2x' + 7x = 0$ . Give your answer in matrix form.

**Solution:** Let  $y = x'$ , The differential equation becomes

$$y' + 2y + 7x = 0 \quad \Rightarrow \quad y' = -7x - 2y.$$

The companion system is

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -7 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

(c) (4) Consider the set of all series of the form  $\frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos(nt) + \sum_{n=1}^{\infty} b_n \sin(nt)$ . Here,  $a_0, a_n, b_n$  are parameters that can take arbitrary values. Is this set a vector space?

**Solution:** Yes. Clearly this set is closed under addition and scalar multiplication.

(d) (4) **True or false:** Suppose  $A$  is a square matrix. If the linear system  $A\mathbf{x} = \mathbf{0}$  has more than one solution, then  $\det A = 0$ .

**Solution:**  True. More than one solution means the null space of  $A$  is nontrivial. So  $A$  is not invertible, which implies  $\det(A) = 0$ .

(e) (4) Suppose  $E$  is a  $2 \times 2$  matrix with eigenvalues 1 and -3 and corresponding eigenvectors  $\begin{bmatrix} 3 \\ 5 \end{bmatrix}$ ,  $\begin{bmatrix} 7 \\ 2 \end{bmatrix}$ .

Suppose  $\begin{bmatrix} x \\ y \end{bmatrix}$  is a solution to the system  $\mathbf{x}' = E\mathbf{x}$ . As  $t$  gets large, the ratio of  $x$  to  $y$  goes asymptotically to what value?

**Solution:**  3/5.  $\mathbf{x} = c_1 e^t \begin{bmatrix} 3 \\ 5 \end{bmatrix} + c_2 e^{-3t} \begin{bmatrix} 7 \\ 2 \end{bmatrix}$ . As  $t$  gets large the second term goes to 0, so we have  $x \approx 3c_1 e^t$  and  $y \approx 5c_1 e^t$ . Therefore, the ratio  $x/y$  becomes  $3/5$ .

End of quiz solutions

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ES.1803 Differential Equations

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