i-theory: visual cortex and deep networks

The Center for Brains, Minds and Machines

tomaso poggio, CBMM, BCS, CSAIL, McGovern MIT

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Theoretical/conceptual framework for vision

- The first 100ms of vision: feedforward and invariant: what, who, where
- Top-down needed for verification step and more complex questions: generative models, probabilistic inference, top-down visual routines.

Following this conceptual framework we are working on:

1.theory of invariance in feedforward networks (visual cortex)
 2.a generative approach, probabilistic in nature
 3.visual routines, and of how they may be learned.



Computational Vision



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Object recognition

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Source: Wallisch, Pascal, and J. Anthony Movshon. "Structure and function come unglued in the visual cortex." Neuron 60, no. 2 (2008): 195-197.

Vision: what is where

- Human Brain
 - -10^{10} - 10^{11} neurons (~1 million flies)
 - -10¹⁴- 10¹⁵ synapses

- Ventral stream in rhesus monkey
 - ~10⁹ neurons in the ventral stream
 (350 10⁶ in each hemisphere)
 - ~15 10⁶ neurons in AIT (Anterior InferoTemporal) cortex
- ~200M in V1, ~200M in V2, 50M in V4

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Recognition in Visual Cortex: "classical model", selective and invariant



Source: Serre, Thomas, Minjoon Kouh, Charles Cadieu, Ulf Knoblich, Gabriel Kreiman, and Tomaso Poggio. A theory of object recognition: Computations and circuits in the feedforward path of the ventral stream in primate visual cortex. No. AI MEMO-2005-036. Massachusetts Institute of Technology Center for Biological and Computational Learning, 2005.

It is in the family of "Hubel-Wiesel" models (Hubel & Wiesel, 1959: *qual.* Fukushima, 1980: *quant*; Oram & Perrett, 1993: *qual*; Wallis & Rolls, 1997; Riesenhuber & Poggio, 1999; Thorpe, 2002; Ullman et al., 2002; Mel, 1997; Wersing and Koerner, 2003; LeCun et al 1998: *not-bio*; Amit & Mascaro, 2003: *not-bio*; Hinton, LeCun, Bengio *not-bio;* Deco & Rolls 2006...)

 As a biological model of object recognition in the ventral stream – from V1 to PFC -- it is *perhaps* the most quantitatively faithful to known neuroscience data

[software available online]

Riesenhuber & Poggio 1999, 2000; Serre Kouh Cadieu Knoblich Kreiman & Poggio 2005; Serre Oliva Poggio 2007

Hierarchical feedforward models of the

ventral stream

Feedforward Models: "predict" rapid categorization (82% model vs. 80% humans)



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Iden

O Simple cells

--- MA3

Complex cells Main routes Bypass routes **S**5

C3

C2b

S3 S2b C2

S2 C1 S1 Why do these networks including DLCNs work so well?

Models are not enough... we need a theory!

Plan

- i-theory (main results)
- equivalence to DCLNs, theory notes on DCLNs
- Some predictions + perspectives in i-theory
- Details and ML remarks

i-theory

Learning of *invariant&selective* Representations in Sensory Cortex



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Source: Wallisch, Pascal, and J. Anthony Movshon. "Structure and function come unglued in the visual cortex." Neuron 60, no. 2 (2008): 195-197.





VGG (2014) - 6.8% Baidu (2015) - 5.33% AlexNet (2012) - 15.3% Clarifai (2013) - 11.7%

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What i-theory can answer for you

- why some hierarchical nets work well
- what is visual cortex computing?
- function and circuits of simple-complex cells
- why Gabor-like tuning in simple cells?



Courtesy of Tomaso Poggio, Jim Mutch, Fabio Anselmi, Andrea Tacchetti, Lorenzo Rosasco and Joel Leibo. Used with permission.

Source: Poggio, Tomaso, Jim Mutch, Fabio Anselmi, Andrea Tacchetti, Lorenzo Rosasco, and Joel Z. Leibo. "Does invariant recognition predict tuning of neurons in sensory cortex?" (2013).

- why generic, Gabor-like tuning in early areas <u>and</u> specific selective tuning higher up?
- what is the computational reason for the eccentricity-dependent size of RFs in V1, V2, V4?
- what are the roles of back projections?

i-theory: exploring a new hypothesis

A main computational goal of the *feedforward* ventral stream hierarchy — and of vision — is to compute a representation for each incoming image which is invariant to transformations previously experienced in the visual environment.

Empirical demonstration: invariant representation leads to lower sample complexity for a supervised classifier

Theorem (translation case) Consider a space of images of dimensions $d \times d$ pixels which may appear in any position within a window of size $rd \times rd$ pixels. The usual image representation yields a sample complexity (of a linear classifier) o f order $m = O(r^2 d^2)$; the oracle representation (invariant) yields (because of much smaller covering numbers) a sample complexity of order

$$m_{oracle} = O(d^2) = \frac{m_{image}}{r^2}$$



Courtesy of Elsevier, Inc., http://www.sciencedirect.com. Used with permission. Source: Anselmi, Fabio, Joel Z. Leibo, Lorenzo Rosasco, Jim Mutch, Andrea Tacchetti, and Tomaso Poggio. "Unsupervised learning of invariant representations. " Theoretical Computer Science 633 (2016): 112-121.

An algorithm that learns in an unsupervised way to compute invariant representations



Invariant signature from a single image of a new object



















We need only a finite number of projections, K, to distinguish among n images. Similar in spirit to Johnson-Lindestrauss

d(I, I') distance using all templates

 $\hat{d}_{K}(I,I')$ distance using K templates

Suppose we have n images

 $\|d(I, I') - \hat{d}_K(I, I')\| \le \varepsilon$ with probability $1 - \delta^2$ if

$$K \ge \frac{2}{c\varepsilon^2} \log(\frac{n}{\delta})$$

I-Theory

- So far: compact groups in R^2
- I-theory extend proves invariance+uniqueness theorems for
 - partially observable groups
 - non-group transformations



Courtesy of NIPS. Used with permission. Source: Liao, Qianli, Joel Z. Leibo, and Tomaso Poggio. "Learning invariant representations and applications to face verification." In Advances in Neural Information Processing Systems, pp. 3057-3065. 2013.

• hierarchies of magic HW modules (multilayer)

Invariance, sparsity, wavelets

Theorem: Sparsity is *necessary and sufficient* condition for translation and scale invariance. Sparsity for translation (respectively scale) invariance is equivalent to the support of the template being small in space (respectively frequency).

Theorem: Maximum simultaneous invariance to translation and scale is achieved by Gabor templates:

$$t(x) = e^{-\frac{x^2}{2\sigma^2}} e^{i\omega_0 x}$$

Non-group transformations: approximate invariance in class-specific regime

 $\mu_n^k(I)$ is locally invariant if:

- *I* is sparse in the dictionary of t^k
- I transforms in the same way (belong to the same class) as t^k
- the transformation is sufficiently smooth



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Local and global invariance: whole-parts theorem



Source: Serre, Thomas, Minjoon Kouh, Charles Cadieu, Ulf Knoblich, Gabriel Kreiman, and Tomaso Poggio. A theory of object recognition: Computations and circuits in the feedforward path of the ventral stream in primate visual cortex. No. AI MEMO-2005-036. Massachusetts Institute of Technology Center for Biological and Computational Learning, 2005.

For any signal (image) there is a layer in the hierarchy such that the response is invariant w.r.t. the signal transformation.

biophysics: prediction on simple-complex cell



Basic machine: a HW module

(dot products and histograms/moments for image seen through RF)

• The cumulative histogram (empirical cdf) can be be computed as



• This maps directly into a set of simple cells with threshold $n\Delta$

• ...and a complex cell indexed by n and k summating the simple cells

The nonlinearity can be rather arbitrary for invariance provided it is stationary in time

Robust and bio plausible

- nonlinearity can be almost anything
- pooling is average but softmax is OK
- low bit precision
- Details and ML remarks



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Resource: Brains, Minds and Machines Summer Course Tomaso Poggio and Gabriel Kreiman

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